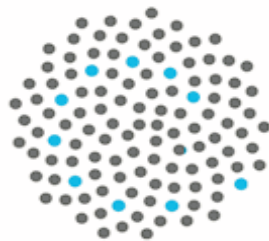


# Quasi-stationary Distributions

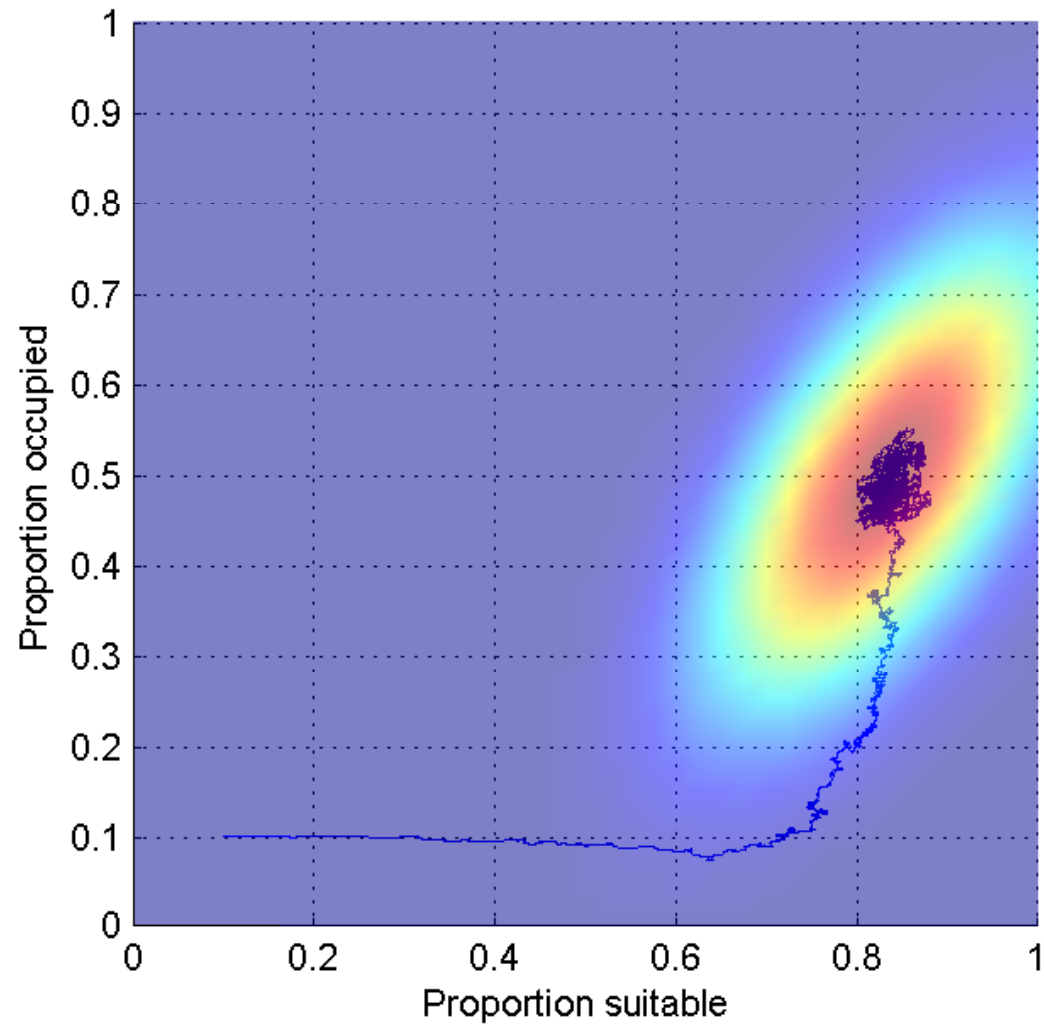
Phil Pollett

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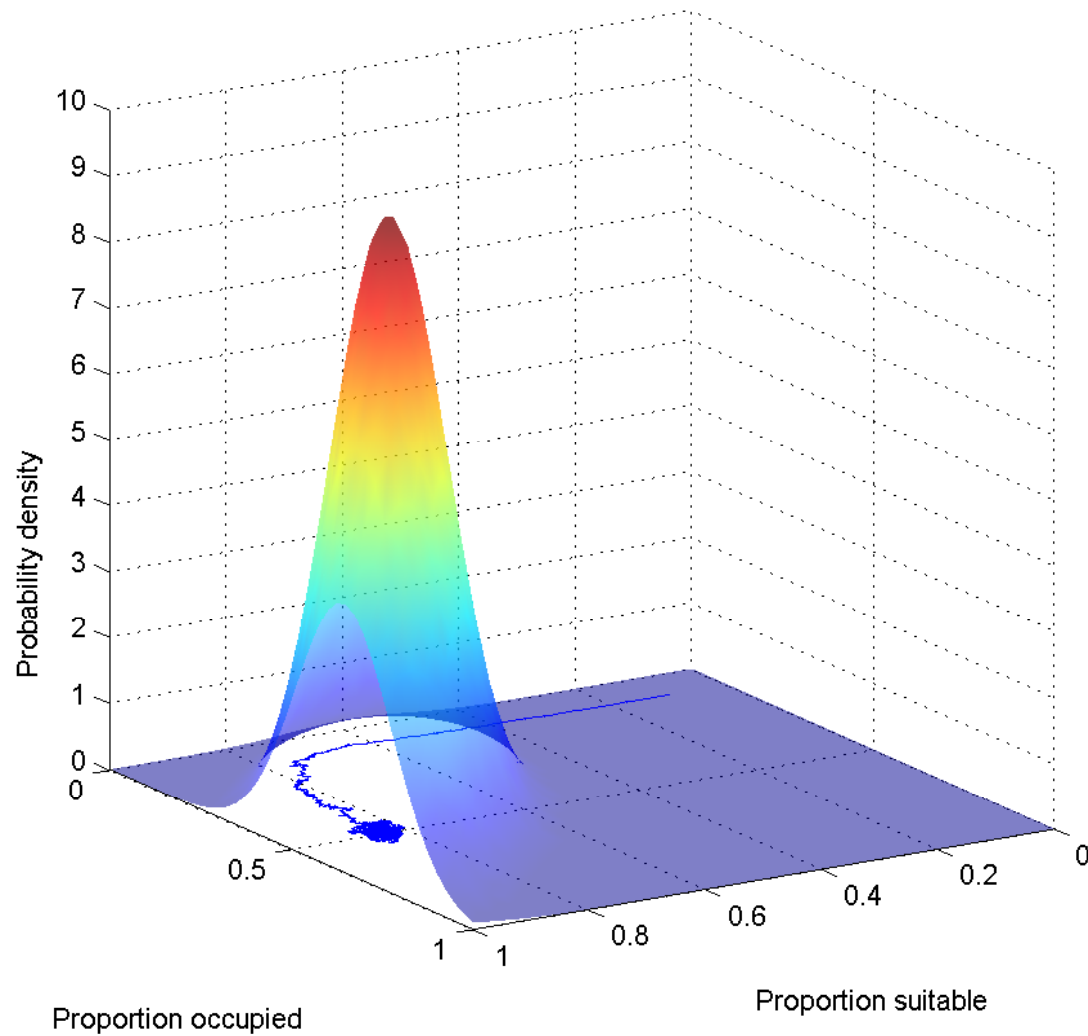


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# Habitat dynamics



# Habitat dynamics



# Habitat dynamics

A continuous-time Markov chain  $\{(m(t), n(t)), t \geq 0\}$ .

- $S = \{(m, n) : 0 \leq n \leq m \leq M\}$
- $m$  = the number of suitable patches
- $n$  = the number of occupied patches
- $M$  = the total number of patches (fixed)
- Transition rates  $\{q(x, y), x, y \in S\}$ :

$$q((m, n), (m + 1, n)) = r(M - m)$$

$$q((m, n), (m - 1, n)) = s(m - n)$$

$$q((m, n), (m - 1, n - 1)) = sn$$

$$q((m, n), (m, n + 1)) = c \frac{n}{M} (m - n)$$

$$q((m, n), (m, n - 1)) = en$$

# Metapopulation network

A continuous-time Markov chain  $\{(n_1(t), \dots, n_M(t)), t \geq 0\}$ .

- $S = \{0, \dots, N_1\} \times \dots \times \{0, \dots, N_M\}$
- $n_i$  = the patch- $i$  population size (capacity  $N_i$ )
- $M$  = the total number of patches (fixed)
- Transition rates  $\{q(x, y), x, y \in S\}$ :

$$q(n, n + e_i) = b \frac{n_i}{N_i} (N_i - n_i)$$

$$q(n, n - e_i + e_j) = \gamma_{ij} \frac{n_i}{N_j} (N_j - n_j) \quad (j \neq i)$$

$$q(n, n - e_i) = \mu n_i.$$

Here  $b$  is the local birth rate,  $\gamma_{ij}$  is the rate of migration from patch  $i$  to patch  $j$ , and  $\mu$  is the per-capita death rate.

# An auto-catalytic reaction

Consider the reaction  $A \xrightarrow{X} B$ , where  $X$  is a catalyst.

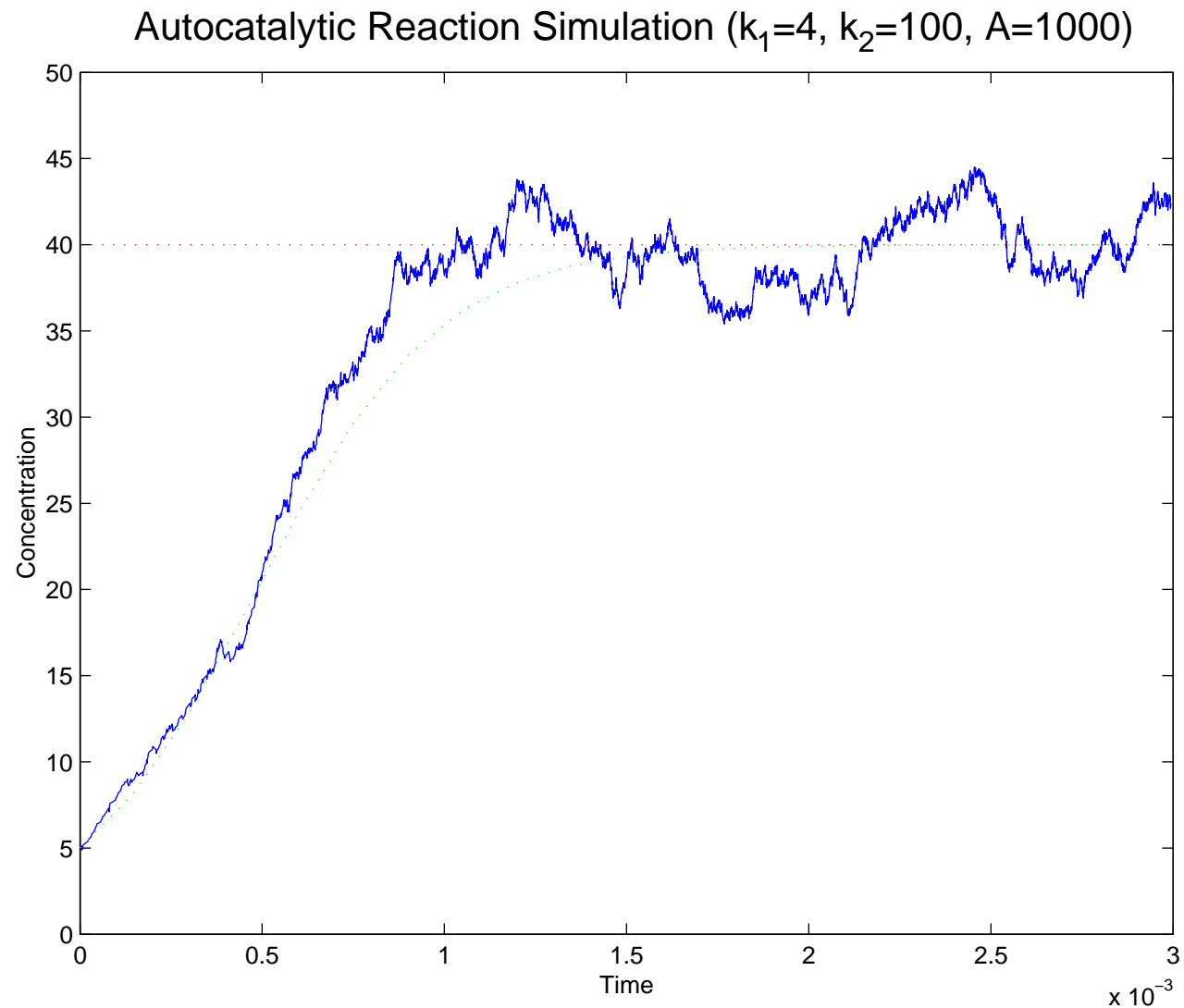
A two stage (auto-catalytic) scheme:



Let  $X(t)$  = number of  $X$  molecules at time  $t$ . Suppose that the concentration of  $A$  is held constant; let  $a$  be the number of molecules of  $A$ . The state space is  $S = \{0, 1, 2, \dots\}$  and the transition rates are:

$$q_{ij} = \begin{cases} k_1 a i & \text{if } j = i + 1 \\ k_2 \binom{i}{2} & \text{if } j = i - 2 \\ 0 & \text{otherwise.} \end{cases}$$

# An auto-catalytic reaction



# Ingredients

- A (time-homogeneous) **Markov chain**  $(X(t), t \geq 0)$  in **continuous time**, taking values in  $S = \{0, 1, 2, \dots\}$ .
- **Transition rates**  $Q = \{q_{ij}, i, j \in S\}$ :  $q_{ij} (\geq 0)$ , for  $j \neq i$ , is the transition rate from state  $i$  to state  $j$  and  $q_{ii} = -q_i$ , where  $q_i = \sum_{j \neq i} q_{ij} (< \infty)$  is the transition rate out of state  $i$ .
- **Assumptions**: For simplicity, take 0 to be the sole absorbing state (that is,  $q_{0j} = 0$ ), suppose that  $C = \{1, 2, \dots\}$  is irreducible and that we reach 0 from  $C$  **with probability 1**.
- **Transition probabilities**:  $P(t) = \{p_{ij}(t), i, j \in S\}$ , where  $p_{ij}(t) = \Pr(X(t) = j | X(0) = i)$ . **State probabilities**:  $p(t) = \{p_j(t), j \in S\}$ , where  $p_j(t) = \Pr(X(t) = j)$ .



# Ingredients

- **Initial distribution**:  $a = (a_j, j \in S)$  ( $a_0 = 0$ ).
- **Forward equations**: the state probabilities satisfy  $p'(t) = p(t)Q$ ,  $p(0) = a$ . In particular, since  $q_{0j} = 0$ ,

$$p'_j(t) = \sum_{i \in C} p_i(t)q_{ij}, \quad j \in S, \quad t > 0.$$

- **Conditional state probabilities**: define  $m(t) = (m_j(t), j \in C)$  by

$$m_j(t) = \Pr(X(t) = j \mid X(t) \in C) = \frac{p_j(t)}{\sum_{k \in C} p_k(t)},$$

the chance of being in state  $j$  *given that the process has not reached 0*.

# Quasi-stationary distributions

**Question 1.** Does  $m(t) \rightarrow m$  as  $t \rightarrow \infty$ ?

**Question 2.** Can we choose the initial distribution  $a$  in order that  $m_j(t) = a_j$ ,  $j \in C$ , for all  $t > 0$ ?

**Definition.** A distribution  $m = (m_j, j \in C)$  satisfying  $m(t) = m$  for all  $t > 0$  is called a *quasi-stationary distribution* (QSD).

If  $m(t) \rightarrow m$  then  $m$  is called a *limiting-conditional distribution* (LCD).

**Question 3.** Is the QSD unique?

**Question 4.** When an LCD exists, is it a QSD?

**Question 5.** Does the LCD depend on the initial distribution?

# Origins

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Yaglom proved that the LCD exists for the subcritical (Galton-Watson) branching process (in discrete time) starting from a single initial ancestor:

A.M. Yaglom (1947) Certain limit theorems of the theory of branching processes (in Russian). *Dokl. Acad. Nauk SSSR* 56, 795–798.

The moment condition [finite variance of the number of offspring] was removed by Joffe (1967) and Heathcote, Seneta and Vere-Jones (1967).

Even earlier, Kolmogorov (1938) proved the convergence of the conditional mean number of individuals.

# Origins

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The **finite state space** case was dispensed with early on using Perron Frobenius Theory. The QSD exists uniquely and is the LCD (the same for all initial distributions):

J.N. Darroch and E. Seneta. (1965) On quasi-stationary distributions in absorbing discrete-time Markov chains. *J. Appl. Probab.* 2, 88–100.

J.N. Darroch and E. Seneta. (1967) On quasi-stationary distributions in absorbing continuous-time finite Markov chains. *J. Appl. Probab.* 4, 192–196.

# Everyone knows that ...

**Digression.** Suppose for the moment that  $S$  is irreducible.

- If a **stationary distribution** ( $\pi P(t) = \pi$ ) exists, then it is unique.
- $S$  is recurrent iff  $mP(t) \leq m$  has a positive solution, unique up to constant multiples, which satisfies  $mP(t) = m$  ( $m$  is called an **invariant measure**).
- $mP(t) = m$  implies  $mQ = 0$ . (**Warning:**  $mQ = 0$  does not necessarily imply  $mP(t) = m$ .)
- $\pi Q \leq 0$  implies  $\pi P(t) = \pi$  iff  $Q$  is regular (non-explosive), in which case  $\pi Q = 0$  ( $\pi$  is called an **equilibrium distribution**).
- If  $S$  is recurrent, then  $S$  is **positive** recurrent iff the invariant measure  $m$  is finite ( $\sum_j m_j < \infty$ ), in which case the **limiting distribution** is given by  $\pi_i = m_i / \sum_j m_j$ .

# Open Problem 1

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Develop a satisfactory theory of QSDs/LCDs

# First major advance

Conditions for the existence of LCDs for countable-state Markov chains in discrete time.

E. Seneta and D. Vere-Jones (1966) On quasi-stationary distributions in discrete-time Markov chains with a denumerable infinity of states. *J. Appl. Probab.* 3, 403–434.

D. Vere-Jones (1962) Geometric ergodicity in denumerable Markov chains. *Quart. J. Math. Oxford* 13, 7–28.

The  $R$ -classification was introduced ( $R$ -recurrent,  $R$ -transient,  $R$ -null recurrent,  $R$ -positive recurrent).

# First major advance

Seneta and Vere-Jones discovered that:

- QSDs may **not be unique**.
- Basically,  $R$ -positive recurrence (to be defined later) is **sufficient** for the existence of an LCD.
- $R$ -positive recurrence is **hard to check**.
- $R$ -positive recurrence is **not necessary** for the existence of an LCD.
- When LCDs exist, **they may depend on the initial distribution** (Galton-Watson branching process). Sufficient conditions were given for non-dependence.
- There are many **other kinds** of LCDs.



# Continuous time

“Analogous” papers for the continuous-time case:

D. Vere-Jones (1969) Some limit theorems for evanescent processes. *Austral. J. Statist.* 11, 67–78.

J.F.C. Kingman (1963) The exponential decay of Markov transition probabilities. *Proc. London Math. Soc.* 13, 337–358.

The LCD can exist in the  $\lambda$ -transient case (continuous-time analogue of  $R$ -transient):

E. Seneta (1966) Quasi-stationary behaviour in the random walk with continuous time. *Austral. J. Statist.* 8, 92–98.

# $\lambda$ -classification

Following Vere-Jones (1962), Kingman (1963) proved that the limit

$$\lambda (= \lambda_C) = \lim_{t \rightarrow \infty} -\frac{1}{t} \log p_{ij}(t)$$

exists and is the same for all  $i, j \in C$ , where  $C$  is any irreducible class. This limit satisfies

- $0 \leq \lambda < \infty$ ,
- $p_{ii}(t) \leq e^{-\lambda t}$ ,  $i \in C$ , and indeed
- $p_{ij}(t) \leq M_{ij} e^{-\lambda t}$ ,  $i, j \in C$ , for suitable constants  $M_{ij}$ .

$\lambda$  is called the *decay parameter* (of  $C$ ).

# $\lambda$ -classification

The irreducible class  $C$  is said to be  $\lambda$ -recurrent if

$$\int_0^{\infty} e^{\lambda t} p_{ij}(t) dt = \infty$$

for some (and then all)  $i, j \in C$ . Otherwise,  $C$  is  $\lambda$ -transient.

A  $\lambda$ -recurrent class  $C$  is called  $\lambda$ -null recurrent if  $e^{\lambda t} p_{ij}(t) \rightarrow 0$  as  $t \rightarrow \infty$  for some (and then all)  $i, j \in C$ . It is called  $\lambda$ -positive recurrent if  $e^{\lambda t} p_{ij}(t) \rightarrow m_{ij}$  (strictly positive constants) for some (and then all)  $i, j \in C$ .

# $\lambda$ -classification

For each irreducible class  $C$  there always exist  $\lambda$ -subinvariant quantities:

$\lambda$ -subinvariant measure  $m = (m_j, j \in C)$ :

$$\sum_{i \in C} m_i p_{ij}(t) \leq e^{-\lambda t} m_j, \quad j \in C, t \geq 0.$$

$\lambda$ -subinvariant vector (function)  $x = (x_j, j \in C)$ :

$$\sum_{i \in C} p_{ji}(t) x_i \leq e^{-\lambda t} x_j, \quad j \in C, t \geq 0.$$

These quantities are called  $\lambda$ -invariant if equality holds for some (and then all)  $j \in C$ .

# $\lambda$ -classification

The irreducible class  $C$  is  $\lambda$ -recurrent *iff* the  $\lambda$ -subinvariant measure  $m$  and the  $\lambda$ -subinvariant vector  $x$  are unique and  $\lambda$ -invariant:

$$\sum_{i \in C} m_i p_{ij}(t) = e^{-\lambda t} m_j, \quad \sum_{i \in C} p_{ji}(t) x_i = e^{-\lambda t} x_j.$$

If  $C$  is  $\lambda$ -recurrent, then it is  $\lambda$ -positive recurrent *iff*  $\sum_{k \in C} m_k x_k < \infty$ , in which case

$$\lim_{t \rightarrow \infty} e^{\lambda t} p_{ij}(t) = \frac{x_i m_j}{\sum_{k \in C} m_k x_k}, \quad i, j \in C.$$

# Significance of $\lambda$ -positivity

$$\begin{aligned} m_{ij}(t) &:= \Pr(X(t) = j | X(t) \in C, X(0) = i) \\ &= \frac{\Pr(X(t) = j | X(0) = i)}{\Pr(X(t) \in C | X(0) = i)} \\ &= \frac{p_{ij}(t)}{\sum_{k \in C} p_{ik}(t)} = \frac{e^{\lambda t} p_{ij}(t)}{\sum_{k \in C} e^{\lambda t} p_{ik}(t)} \end{aligned}$$

So, formally,  $m_{ij}(t) \rightarrow \frac{x_i m_j}{\sum_{k \in C} x_i m_k} = \frac{m_j}{\sum_{k \in C} m_k}$ .

In fact, if  $C$  is  $\lambda$ -positive recurrent, then, for each  $i$ ,  $m_{ij}(t) \rightarrow m_j / \sum_{k \in C} m_k$ , where  $m = (m_j, j \in C)$  is the (essentially unique)  $\lambda$ -invariant measure (with the interpretation that the limit is 0 if  $\sum_{k \in C} m_k = \infty$ ).

# Strong ratio limit property

Since  $e^{\lambda t} p_{ij}(t) \rightarrow x_i m_j / \sum_{k \in C} m_k x_k$ ,  $i, j \in C$ , when  $C$  is  $\lambda$ -positive recurrent, we have that

$$\frac{p_{ij}(s+t)}{p_{kl}(t)} \rightarrow e^{-\lambda s} \frac{x_i m_j}{x_k m_l}, \quad i, j, k, l \in C, \quad s \geq 0.$$

This *strong ratio limit property* may hold in the  $\lambda$ -null recurrent case (Orey (1961), Kingman and Orey (1964), Pruitt (1965), Folkman and Port (1966), Papangelou (1967) and Kersting (1974, 1976), and even the  $\lambda$ -transient case (Kesten (1963))).

F. Papangelou (1968) Strong ratio limits,  $R$ -recurrence and mixing properties of discrete parameter Markov processes. *Z. Wahrscheinlichkeitstheorie und Verw. Gebiete* 8, 259–297.

# Strong ratio limit property

Note that  $\lambda$ -positive recurrence also implies

$$\frac{\Pr(T > t + s | X(0) = i)}{\Pr(T > t | X(0) = k)} = \frac{\sum_{j \in C} p_{ij}(s + t)}{\sum_{j \in C} p_{kj}(t)} \rightarrow e^{-\lambda s} \frac{x_i}{x_k},$$

where  $T$  is the time to absorption. This again holds more generally:

S.D. Jacka, and G.O. Roberts (1995) Weak convergence of conditioned processes on a countable state space. *J. Appl. Probab.* 32, 902–916.

Key to conditioned *process limits*.



# Summary

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This is all very unsatisfactory.

- $\lambda$ -classification is (surprisingly) not the key to the existence of a LCD.
- The SRLP appears to be the key (but illudes us).
- When the LCD exists for a given starting state, it is a (the?)  $\lambda$ -invariant probability measure for  $P$ .
- The LCD may depend on the initial distribution.
- We need criteria in terms of the transition rates  $Q$ , and criteria we can check.

# Birth-death processes

The LCD exists for all starting states iff  $\lambda > 0$  (just like Yaglom's Theorem):

P. Good (1968) The limiting behaviour of transient birth and death processes conditioned on survival. *J. Austral. Math. Soc. Ser. B* 8, 716–722.

Unfortunately *wrong!* Corrected in:

E.A. van Doorn (1991) Quasi-stationary distributions and convergence to quasi-stationarity of birth-death processes. *Adv. Appl. Probab.* 23, 683–700.

But, unlike for branching processes, we do not know  $\lambda$  explicitly. The LCD was given by van Doorn in terms of the (Karlin and McGregor) orthogonal polynomials.

# Fresh start

Recall the definitions of QSD and LCD in terms of the conditional state probabilities  $m(t) = (m_j(t), j \in C)$ :

$$m_j(t) = \Pr(X(t) = j \mid X(t) \in C) = \frac{\Pr(X(t) = j)}{\Pr(X(t) \in C)} = \frac{p_j(t)}{\sum_{k \in C} p_k(t)}$$

the chance of being in state  $j$  given that the process has not reached 0.

**Definition.** A distribution  $m = (m_j, j \in C)$  satisfying  $m(t) = m$  for all  $t > 0$  is called a *quasi-stationary distribution* (QSD). If  $m(t) \rightarrow m$  then  $m$  is called a *limiting-conditional distribution* (LCD).

# Characterizing QSDs

Since  $a$  is the initial distribution (with  $a_0 = 0$ ),

$$p_j(t) = \Pr(X(t) = j) = \sum_{i \in C} a_i p_{ij}(t), \quad j \in C, t > 0,$$

where  $p_{ij}(t) = \Pr(X(t) = j | X(0) = i)$ . Therefore, if  $m$  is a QSD, then

$$\sum_{i \in C} m_i p_{ij}(t) = p_j(t) = g(t) m_j, \quad j \in C, t > 0,$$

where  $g(t) = \sum_{k \in C} p_k(t)$ . It is easy to show that  $g$  satisfies:  
 $g(s + t) = g(s)g(t)$ ,  $s, t \geq 0$ , and  $0 < g(t) < 1$ . Thus,  $g(t) = e^{-\mu t}$ ,  
for some  $\mu > 0$ . The converse is also clearly true.

# QSDs and $\mu$ -invariant measures

We have proved the following simple result:

**Proposition.** A probability distribution  $m = (m_j, j \in C)$  is a QSD iff, for some  $\mu > 0$ ,  $m$  is a  $\mu$ -invariant measure, that is

$$\sum_{i \in C} m_i p_{ij}(t) = e^{-\mu t} m_j, \quad j \in C, t \geq 0. \quad (1)$$

Note that for (1) it is necessary that  $\mu \leq \lambda$ , where recall that  $\lambda$  is the decay parameter of  $C$  (Vere-Jones (1969)).

But, can we determine QSDs  $m$  from  $Q$ ?

# Characterization in terms of $Q$

Rewrite (1) as

$$\sum_{i \in C: i \neq j} m_i p_{ij}(t) = ((1 - p_{jj}(t)) - (1 - e^{-\mu t})) m_j$$

and use the fact that  $q_{ij}$  is the right-hand derivative of  $p_{ij}(\cdot)$  near 0. On dividing by  $t$  and letting  $t \downarrow 0$ , we get (formally)

$$\sum_{i \in C: i \neq j} m_i q_{ij} = (q_j - \mu) m_j, \quad j \in C,$$

or, equivalently,

$$\sum_{i \in C} m_i q_{ij} = -\mu m_j, \quad j \in C.$$

# Characterization in terms of $Q$

Accordingly, we shall say that  $m$  is a  $\mu$ -invariant measure for  $Q$  whenever

$$\sum_{i \in C} m_i q_{ij} = -\mu m_j, \quad j \in C.$$

**Theorem.** If  $m$  is a  $\mu$ -invariant measure for  $P$  ( $\mu > 0$ ), then  $m$  is a  $\mu$ -invariant measure for  $Q$ .

R.L. Tweedie (1974) Some ergodic properties of the Feller minimal process. *Quart. J. Math. Oxford* 25, 485–495.

**Corollary.** If  $m$  is a QSD then, for some  $\mu > 0$ ,  $m$  is a  $\mu$ -invariant measure for  $Q$ .

# Characterization in terms of $Q$

Is the converse true? Suppose that, for some  $\mu > 0$ ,  $m$  is a  $\mu$ -invariant measure for  $Q$ , that is

$$\sum_{i \in C} m_i q_{ij} = -\mu m_j, \quad j \in C.$$

Is  $m$  a  $\mu$ -invariant measure for  $P$ ? (So that if  $m$  is a probability measure, then  $m$  is a QSD).

Sum this equation over  $j \in C$ : we get (formally), in the case when  $m$  is a probability measure,

$$\sum_{i \in C} m_i q_{i0} = - \sum_{i \in C} m_i \sum_{j \in C} q_{ij} = - \sum_{j \in C} \sum_{i \in C} m_i q_{ij} = \mu \sum_{j \in C} m_j = \mu.$$



# Characterization in terms of $Q$

**Theorem.** Let  $m = (m_j, j \in C)$  be a probability distribution over  $C$  and suppose that  $m$  is a  $\mu$ -invariant measure for  $Q$ . Then,  $\mu \leq \sum_{j \in C} m_j q_{j0}$  with equality iff  $m$  is a QSD.

P.K. Pollett (1995) The determination of quasi-stationary distributions directly from the transition rates of an absorbing Markov chain. *Math. Computer Modelling* 22, 279–287.

So, in order to determine QSDs we must solve

$$\sum_{i \in C} m_i q_{ij} = - \left( \sum_{k \in C} m_k q_{k0} \right) m_j, \quad j \in C.$$

# Example: catastrophe process

Suppose that

$$\begin{aligned}q_{i,i+1} &= a\rho i, & i \geq 0, \\q_{i,i} &= -\rho i, & i \geq 0, \\q_{i,i-k} &= \rho i b_k, & i \geq 2, k = 1, 2, \dots, i-1, \\q_{i,0} &= \rho i \sum_{k=i}^{\infty} b_k, & i \geq 1,\end{aligned}$$

where  $\rho, a > 0$ ,  $b_i > 0$  for at least one  $i \geq 1$  and  $a + \sum_{i=1}^{\infty} b_i = 1$ . Jumps occur at a constant per-capita rate  $\rho$  and, at a jump time, a birth occurs with probability  $a$ , or otherwise a catastrophe occurs, the size of which is determined by the probabilities  $b_i$ ,  $i \geq 1$ . Clearly, 0 is an absorbing state and  $C = \{1, 2, \dots\}$  is an irreducible class.

*Does  $Q$  admit a QSD?*

# Example: catastrophe process

On substituting the transition rates into the equations  $\sum_{i \in C} m_i q_{ij} = -\mu m_j$ ,  $j \in C$ , we get:

$$-(\rho - \mu)m_1 + \sum_{k=2}^{\infty} k\rho b_{k-1}m_k = 0,$$

and, for  $j \geq 2$ ,

$$(j - 1)\rho a m_{j-1} - (j\rho - \mu)m_j + \sum_{k=j+1}^{\infty} k\rho b_{k-j}m_k = 0.$$

# Example: catastrophe process

If we try a solution of the form  $m_j = t^j$ , the first equation tells us that  $\mu = -\rho(f'(t) - 1)$ , where

$$f(s) = a + \sum_{i \in C} b_i s^{i+1}, \quad |s| \leq 1,$$

and, on substituting both of *these* quantities in the second equation, we find that  $f(t) = t$ . This latter equation has a unique solution  $\sigma$  on  $[0, 1]$ . Thus, by setting  $t = \sigma$  we obtain a positive  $\mu$ -invariant measure  $m = (m_j, j \in C)$  for  $Q$ , which satisfies  $\sum_{j \in C} m_j = 1$  whenever  $\sigma < 1$ .

The condition  $\sigma < 1$  is satisfied only in the subcritical case, that is, when (the drift)  $D = a - \sum_{i \in C} i b_i < 0$ ; this also guarantees that absorption occurs with probability 1.

# Example: catastrophe process

Further, it is easy to show that  $\sum_{i \in C} m_i q_{i0} = \mu$ :

$$\begin{aligned}\sum_{i \in C} m_i q_{i0} &= \sum_{i=1}^{\infty} (1 - \sigma) \sigma^{i-1} \rho i \sum_{k=i}^{\infty} b_k \\ &= \rho \sum_{k=1}^{\infty} b_k \sum_{i=1}^k (1 - \sigma) i \sigma^{i-1} \\ &\quad \vdots \\ &= \rho(1 - f'(\sigma)) = \mu.\end{aligned}$$

**Proposition.** (Pakes (1987)) The subcritical birth-death and catastrophe process has a *geometric* QSD  $m = (m_j, j \in C)$ . This is given by  $m_j = (1 - \sigma) \sigma^{j-1}$ ,  $j \in C$ , where  $\sigma$  is the unique solution to  $f(t) = t$  on the interval  $[0, 1]$ .

# Characterization in terms of $Q$

There are more general necessary and sufficient conditions.

P.K. Pollett (1986) On the equivalence of  $\mu$ -invariant measures for the minimal process and its  $q$ -matrix.  
*Stochastic Process. Appl.* 22, 203–221.

**Theorem.** A  $\mu$ -invariant measure  $m$  for  $Q$  is  $\mu$ -invariant for  $P$  iff the equations

$$\sum_{i \in C} y_i q_{ij} = \nu y_j, \quad 0 \leq y_j \leq m_j, \quad j \in C,$$

have no non-trivial solution for some (and then for all)  $\nu > -\mu$ .

# Characterization in terms of $Q$

Because of the similarity with Reuter's (1957) condition for there to be a unique solution to the forward equations, we came up with the following (Hart and Pollett (1996)):

**Corollary.** (*The Reuter FE Condition*) If the equations

$$\sum_{i \in C} y_i q_{ij} = \nu y_j, \quad j \in C,$$

have no non-trivial, non-negative solution such that  $\sum_{j \in C} y_j < \infty$ , for some (and then for all)  $\nu > 0$ , then *all*  $\mu$ -invariant probability measures for  $Q$  are  $\mu$ -invariant measures (and hence QSDs) for  $P$ .

# Birth-death processes

We are given strictly positive birth rates  $(\lambda_j, j \in C)$  ( $\lambda_0 = 0$  since 0 is absorbing) and death rates  $(\mu_j, j \in C)$ . We have assumed that absorption occurs with probability 1, that is,

$$\sum_{i=1}^{\infty} \frac{1}{\lambda_i \pi_i} = \infty,$$

where  $\pi_1 = 1$  and, for  $j \geq 2$ ,

$$\pi_j = \prod_{i=2}^j \frac{\lambda_{i-1}}{\mu_i}.$$



# Birth-death processes

Erik van Doorn proved the following characterization, extending early work of Cavender (1978), in terms of

$$D := \sum_{i=1}^{\infty} \frac{1}{\lambda_i \pi_i} \sum_{j=i+1}^{\infty} \pi_j.$$

**Theorem.** If  $D = \infty$ , then either  $\lambda = 0$  and there is no QSD, or  $\lambda > 0$  and there is a *one-parameter family* of QSDs, being the normalized  $\mu$ -invariant measures ( $0 < \mu \leq \lambda$ ). If  $D < \infty$ , then  $\lambda > 0$  and there is *exactly one* QSD, being the normalized  $\lambda$ -invariant measure.

E.A. van Doorn (1991) Quasi-stationary distributions and convergence to quasi-stationarity of birth-death processes. *Adv. Appl. Probab.* 23, 683–700.

# Existence of QSDs

Since  $D = \infty$  (for birth-death processes) is *arithmetically equivalent* to the Reuter FE condition, we have the following conjecture for our absorbing Markov chain:

**Conjecture.** If the Reuter FE Condition holds, then either  $\lambda = 0$  and there is no QSD, or  $\lambda > 0$  and there is a one-parameter family of QSDs. If the Reuter FE Condition fails, then  $\lambda > 0$  and there is *exactly one* QSD.

**Conjecture.** If  $\lim_{i \rightarrow \infty} E(T|X(0) = i) = \infty$ , then either  $\lambda = 0$  and there is no QSD, or  $\lambda > 0$  and there is a one-parameter family of QSDs. If  $\lim_{i \rightarrow \infty} E(T|X(0) = i) < \infty$ , then  $\lambda > 0$  and there is *exactly one* QSD.

**Conjecture.** The above conjectures are the same!

# Existence of QSDs and LCDs

Suppose that  $E(T|X(0) = i) < \infty$ . The existence of a QSD is guaranteed under *asymptotic remoteness* (AR):

$$\lim_{i \rightarrow \infty} \Pr(T > t | X(0) = i) = 1.$$

P. Ferrari, H. Kesten, S. Martínez, and P. Picco (1995) Existence of quasi-stationary distributions. A renewal dynamic approach. *Ann. Probab.* 23, 501–521.

**Theorem.** Under AR a QSD exists iff  $\lambda > 0$ . If  $Q$  is bounded ( $\sup_i q_i < \infty$ ), the LCD exists.

(Note the absence of  $\lambda$ -classification in the latter.)

But (Pakes (1995)), *AR can be arbitrarily badly violated*: even  $\lim_{i \rightarrow \infty} \Pr(T > t | X(0) = i) = 0$ .

# Killer blow

Recall the Good (1968)–Van Doorn (1991) result for birth-death process and Yaglom’s theorem for branching processes: the LCD exists iff  $\lambda > 0$ . And, for  $Q$  bounded AR is sufficient (Ferrari, et al. (1995)).

H. Kesten (1995) A ratio limit theorem for (sub) Markov chains on  $\{1, 2, \dots\}$  with bounded jumps. *Adv. Appl. Probab.* 27, 652–691.

Suppose  $Q$  is bounded ( $\sup_i q_i < \infty$ ). If the chain has *bounded jumps* and satisfies a *uniform irreducibility condition*, then there is at most one QSD, and the LCD exists iff  $\lambda > 0$ .

Kesten also provided an example (25 journal pages) for which a QSD exists, but the LCD does not exist.

# Open problems

- Obtain necessary and sufficient conditions in terms of  $Q$  for the SRLP to hold and for the LCD to exist. (Kesten's result and example suggest that this might be difficult.)
- Does Kesten's result hold when  $\sup_i q_i = \infty$ .
- Obtain workable sufficient conditions in terms of  $Q$ .
- Solve the domain of attraction problem. Whilst the answer is known for branching processes, and several examples, it is not known for birth-death processes.
- Obtain necessary and sufficient conditions for  $\lambda > 0$  for various models (solved recently for birth-death processes by Hanjun Zhang).
- Numerical methods: truncation procedures, and the GTH algorithm for dominant eigensolutions.

# Barlett's idea

When the process hits 0, send it back:

M.S. Bartlett (1960) *Stochastic Population Models in Ecology and Epidemiology*, Methuen, London.

In continuous time, we send it back instantaneously. Let  $\nu = (\nu_j, j \in C)$  be a probability measure on  $C$ , and define  $Q^\nu$  by  $q_{ij}^\nu = q_{ij} + q_{i0}\nu_j$ ,  $i, j \in C$ . This is a stable and conservative  $q$ -matrix over  $Q$ . Note, in particular, that  $\sum_{j \in C} q_{ij}^\nu = \sum_{j \in C} q_{ij} + q_{i0} = 0$ . Indeed, the  $Q^\nu$  process is (irreducible and) recurrent, since originally absorption occurred with probability 1; if  $E(T|X(0) = i) < \infty$ , then it is positive recurrent. Let  $\pi$  be its equilibrium distribution ( $\pi Q^\nu = 0$ ). Barlett's idea was to use  $\pi$  to model the long-term behaviour of the original process.

# Barlett's idea

Define a map  $\Phi$  as follows. If  $\nu$  is the “resurrection measure”, and  $\pi$  is the equilibrium distribution of  $Q^\nu$ , let  $\pi = \Phi(\nu)$ .

**Observation.** Any QSD  $m$  satisfying  $E_m(T) < \infty$  is a fixed point of this map ( $m = \Phi(m)$ ) means  $mQ = -\mu m$ , where  $\mu = \sum_{i \in C} m_i q_{i0}$ .

This was exploited by Ferrari, et al. (1995), and also by Clancy and Pollett (2003). We exhibited the map explicitly for birth-death processes and showed that it preserves likelihood-ratio ordering (and hence stochastic ordering). So, for example, if  $\nu^{(1)} \prec^{LR} m \prec^{LR} \nu^{(2)}$ , then  $\Phi^n(\nu^{(1)}) \prec^{LR} m \prec^{LR} \Phi^n(\nu^{(2)})$ . So, bounds on  $m$  can be obtained.

# When absorption is not certain

If  $\alpha_i := \lim_{t \rightarrow \infty} p_{i0}(t) < 1$ , we employ an  $h$ -transform: define transition probabilities  $\bar{P}(t) = \{\bar{p}_{ij}(t), i, j \in S\}$  by  $\bar{p}_{ij}(t) = p_{ij}(t)\alpha_j/\alpha_i$ , and corresponding transition rates  $\bar{Q} = \{\bar{q}_{ij}, i, j \in S\}$  by  $\bar{q}_{ij} = q_{ij}\alpha_j/\alpha_i$ . Then, in an obvious notation,  $\bar{P}(A) = 1$  and  $\mathcal{P}(\cdot | A) = \bar{P}(\cdot)$ , where  $A$  is the event {absorption eventually occurs}. This result can be traced back to Waugh (1958).

Now just reinterpret any given result for  $\bar{P}$ . For example, if  $C$  is  $\lambda$ -positive recurrent and  $\sum_{i \in C} m_i \alpha_i < \infty$ , then

$$\lim_{t \rightarrow \infty} \Pr(X(t) = j \mid X(t) \in C, A) = \frac{m_j \alpha_j}{\sum_{k \in S} m_k \alpha_k},$$

where  $m$  is the essentially unique  $\lambda$ -invariant measure for  $P$ .