

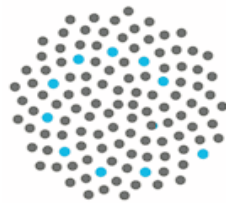
# Limits Theorems for Population Networks with Patch Dependent Extinction Probabilities

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AUSTRALIAN RESEARCH COUNCIL  
Centre of Excellence for Mathematics  
and Statistics of Complex Systems

Ross McVinish  
MASCOS University of Queensland



## Phil Pollett

Mathematical modelling, stochastic process theory and applications: ecology, epidemiology, parasitology, telecommunications and chemical kinetics.

A current project: *Limits theorems for population networks with patch dependent extinction probabilities.*



## Ross McVinish

Lévy processes and stochastic processes displaying long memory, Bayesian nonparametrics, computation for Bayesian statistics and time series analysis.

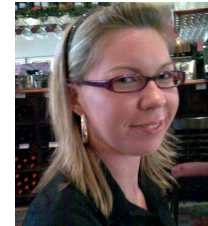
A current project: *Estimation in partially observed large metapopulations.*



# PhD Projects

**Fionnuala Buckley** (April 2007 –)

*Discrete-time Stochastic  
Metapopulation Models*



**Robert Cope** (July 2009 –)

*Animal Movement Between Popula-  
tions Deduced from Family Trees*



**Dejan Jovanović** (March 2009 –)

*Fault Detection in Complex  
and Distributed Systems*



**Aminath Shausan** (July 2010 –)

*Stochastic Models for Epidemics  
in Population Networks*



**Andrew Smith** (July 2009 –)

*Models for Spatially  
Structured Metapopulations*



# Metapopulations

- A metapopulation is a population that is confined to a network of geographically separated habitat patches (for example a group of islands).
- Individual patches may suffer local extinction.
- Recolonization can occur through dispersal of individuals from other patches.

## A Stochastic Patch Occupancy Model (SPOM)

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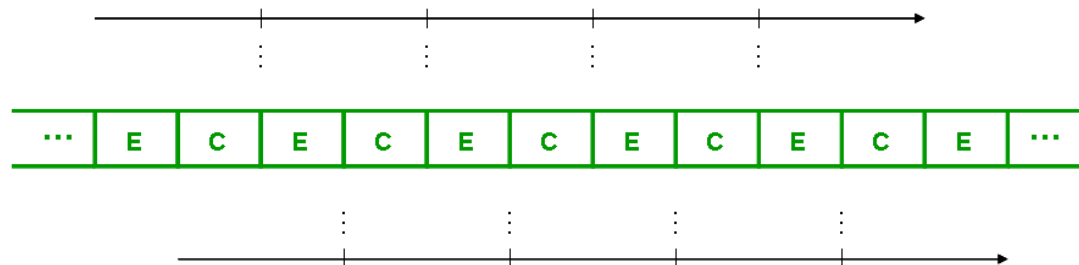
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Thus, we have a *Chain Bernoulli* structure:

$$X_{i,t+1}^{(n)} \stackrel{d}{=} \mathbf{Bin}\left(X_{i,t}^{(n)} + \mathbf{Bin}\left(1 - X_{i,t}^{(n)}, f\left(\frac{1}{n} \sum_{j=1}^n X_{j,t}^{(n)}\right)\right), S_i\right)$$



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*Notation:*  $\text{Bin}(m, p)$  is a binomial random variable with  $m$  trials and success probability  $p$ .

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Compare this with the *homogenous case*, where  $S_i = s$  (non-random) is the same for each  $i$ , and we merely count the *number*  $N_t^{(n)}$  of occupied patches at time  $t$ .

We have the following *Chain Binomial* structure:

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# A deterministic limit

**Theorem\*** If  $N_0^{(n)}/n \xrightarrow{p} x_0$  (a constant), then

$$N_t^{(n)}/n \xrightarrow{p} x_t \quad \text{for all } t \geq 1,$$

where  $(x_t)$  is determined by

$$x_{t+1} = s(x_t + (1 - x_t)f(x_t)).$$

\*Buckley, F.M. and Pollett, P.K. (2010) Limit theorems for discrete-time metapopulation models. *Probability Surveys* 7, 53-83.



# Stability

$$x_{t+1} = s(x_t + (1 - x_t)f(x_t))$$

- **Stationarity:**  $f(0) > 0$ . There is a unique fixed point  $x^* \in [0, 1]$ . It satisfies  $x^* \in (0, 1)$  and is stable.
- **Evanescence:**  $f(0) = 0$  and  $1 + f'(0) \leq 1/s$ . Now 0 is the unique fixed point in  $[0, 1]$ . It is stable.
- **Quasi stationarity:**  $f(0) = 0$  and  $1 + f'(0) > 1/s$ . There are two fixed points in  $[0, 1]$ : 0 (unstable) and  $x^* \in (0, 1)$  (stable).

# A deterministic limit

Returning to the general case, where patch survival probabilities are random and patch dependent, and we keep track of which patches are occupied ...

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First, ...

**Notation:** If  $\sigma$  is a probability measure on  $[0, 1)$  and let  $\bar{s}_k$  denote its  $k$ -th moment, that is,

$$\bar{s}_k = \int_0^1 \lambda^k \sigma(d\lambda).$$



# A deterministic limit

**Theorem** Suppose that there is a probability measure  $\sigma$  and deterministic sequence  $\{d(0, k)\}$  such that

$$\frac{1}{n} \sum_{i=1}^n S_i^k \xrightarrow{p} \bar{s}_k \quad \text{and} \quad \frac{1}{n} \sum_{i=1}^n S_i^k X_{i,0}^n \xrightarrow{p} d(0, k)$$

for all  $k = 0, 1, \dots, T$ . Then, there is a (deterministic) triangular array  $\{d(t, k)\}$  such that, for all  $t = 0, 1, \dots, T$  and  $k = 0, 1, \dots, T - t$ ,

$$\frac{1}{n} \sum_{i=1}^n S_i^k X_{i,t}^n \xrightarrow{p} d(t, k),$$

where

$$d(t + 1, k) = d(t, k + 1) + f(d(t, 0)) (\bar{s}_{k+1} - d(t, k + 1)).$$

# Remarks

- Typically, we are only interested in  $d(t, 0)$ , being the asymptotic proportion of occupied patches.
- However, we may still interpret the ratio  $d(t, k)/d(t, 0)$  ( $k \geq 1$ ) as the  $k$ -th moment of the conditional distribution of the patch survival probability given that the patch is occupied. (From these moments, the conditional distribution could then be reconstructed.)

# Remarks

- When  $\bar{s}_k = \bar{s}_1^k$  for all  $k$ , that is the patch survival probabilities are the same, then it is possible to simplify

$$d(t + 1, k) = d(t, k + 1) + f(d(t, 0)) (\bar{s}_{k+1} - d(t, k + 1)).$$

We can show by induction that  $d(t, k) = \bar{s}_1^k x_t$ , where

$$x_{t+1} = \bar{s}_1 (x_t + (1 - x_t) f(x_t)).$$

(Compare this with the earlier result.)

**Theorem** The fixed points are given by

$$d(k) = \int_0^1 \frac{f(\psi)\lambda^{k+1}}{1-\lambda+f(\psi)\lambda} \sigma(d\lambda),$$

where  $\psi$  solves

$$R(\psi) = \int_0^1 \frac{f(\psi)\lambda}{1-\lambda+f(\psi)\lambda} \sigma(d\lambda) = \psi. \quad (1)$$

If  $f(0) > 0$ , there exists a unique  $\psi > 0$ . If  $f(0) = 0$  and

$$f'(0) \int_0^1 \frac{\lambda}{1-\lambda} \sigma(d\lambda) \leq 1,$$

then  $\psi = 0$  is the unique solution to (1). Otherwise, (1) has two solutions, one of which is  $\psi = 0$ .

**Theorem** If  $f(0) = 0$  and

$$f'(0) \int_0^1 \frac{\lambda}{1-\lambda} \sigma(d\lambda) \leq 1,$$

then  $d(k) \equiv 0$  is a stable fixed point. Otherwise, the non-zero solution to

$$R(\psi) = \int_0^1 \frac{f(\psi)\lambda}{1-\lambda+f(\psi)\lambda} \sigma(d\lambda) = \psi$$

provides the stable fixed point through

$$d(k) = \int_0^1 \frac{f(\psi)\lambda^{k+1}}{1-\lambda+f(\psi)\lambda} \sigma(d\lambda).$$