Improved Sampling Plans for Combinatorial Invariants of Coherent Systems

Radislav Vaisman, Dirk P. Kroese, Ilya B. Gertsbakh

Abstract—Terminal network reliability problems appear in many real-life applications, such as transportation grids, social and computer networks, communication systems, etc. In this paper we focus on monotone binary systems with identical component reliabilities. The reliability of such systems depends only on the number of failure sets of all possible sizes, which is an important system invariant. For large problems, no analytical solution for calculating this invariant in a reasonable time is known to exist, and one has to rely on different approximation techniques. An example of such a method is Permutation Monte Carlo. It is known that this simple plan is not sufficient for adequate estimation of network reliability due to the rare–event problem. As an alternative we propose a different sampling strategy that is based on the recently pioneered Stochastic Enumeration algorithm for tree cost estimation. We show that thanks to its built-in splitting mechanism this method is able to deliver accurate results while employing a relatively modest sample size. Moreover, our numerical results indicate that the proposed sampling scheme is capable of solving problems that are far beyond the reach of the simple Permutation Monte Carlo approach.

Index Terms—System structure function, Network Reliability, Permutation Monte Carlo, Stochastic Enumeration, Rare Events, Splitting.

I. INTRODUCTION

NETWORKS have become an important part of our daily activities and as a consequence a natural question of their reliability and sensitivity comes to light. The network reliability problem can be stated as follows [1]. Suppose we are given an undirected graph $G(V,E,K)$, where $V$ and $E$ are the vertex and edge sets respectively and $K \subseteq V$ is a set of “terminal” nodes. We assume that the vertices are absolutely reliable (that is, they never fail) but that the edges are subject to failure. For $e \in E$ let the corresponding failure probability be $q_e$; that is, $e$ can be in an up or down state with probabilities $p_e = 1 - q_e$ and $q_e$ respectively. Under this setting we can ask for the probability that the terminal set $K$ is connected (network UP state) or disconnected (network DOWN state) [2].

As was noted by Karger [3], the terminal network reliability problem belongs to the #P–complete complexity class. Consequently, it is hard (or even impossible) to solve exactly in polynomial time. The #P complexity class, introduced by Valiant [4] consists of the set of counting problems that are associated

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with a decision problem in NP (non–deterministic polynomial time), e.g., how many solutions does a propositional formula have (#SAT). The #P–complete complexity class is a subclass of #P consisting of those problems in #P to which any other problem in #P can be reduced via a polynomial reduction. #SAT, for example, is #P–complete. Interestingly, various #P–complete problems are associated with an easy decision problem, i.e., the corresponding decision problem is in P (polynomial time), such as satisfiability of propositional formulas in Disjunctive Normal Form (DNF)

For some #P-complete problems there are known efficient approximations. For example, Karp and Luby [5] introduced a fully polynomial randomized approximation scheme (FPRAS) for counting the solutions of DNF satisfiability formulas. Similar results were obtained for the knapsack and permanent counting problems by Dyer and Jerrum et al. [6], [7]. Moreover, Karger [3] obtained a FPRAS for all–terminal network reliability. Unfortunately, there are also many negative results. For example, Dyer et al. and Vadhan [8], [9] showed that counting the number of vertex covers remains hard, even when restricted to planar bipartite graphs of bounded degree or regular graphs of constant degree.

There are two main approaches for tackling such difficult counting problems. The first is Markov Chain Monte Carlo (MCMC) and the second is Sequential Importance Sampling (SIS). Both approaches exploit the finding of Jerrum et al. [10] that counting is equivalent to uniform sampling over a suitably restricted set. MCMC methods sample from such restricted regions by constructing an ergodic Markov chain with stationary and limiting distribution equal to the desired uniform distribution. A number of MCMC approaches with good empirical performance have been proposed; see [11], [12], [13], [14]. Botev et. al. [15] applied a generalized splitting algorithm [11] to handle the terminal network reliability problem.

There are also many examples of successful SIS implementations on various counting problems; see, for example, [5], [16], [17], [18]. More recent advances and background material can be found in [19]. Unsurprisingly, SIS was also applied in context of network reliability, see [20] for details.

In this paper we focus on the estimation of the so-called Spectra or Network Signature [2], [21], [22], [23], [24], [25] measure of a reliability network. The Spectra can be obtained from the number of failure sets of all possible sizes [26], [27], which only depends on the graph topology and is hence a system invariant. The Spectra can be used for several purposes. For example, as soon as the Spectra is available, one can readily calculate the network reliability for any fixed edge failure probability $q$. Moreover, the estimation of Spectra opens a
way for calculating the Birnbaum Importance Measure (BIM) and the Joint Reliability Importance (JRI) of the components. These components importance measures play crucial role in optimal reliability design of coherent systems, see Appendix A and [27] for details.

Unfortunately, the exact Spectra is rarely available analytically. Hence, it is usually estimated via Permutation Monte Carlo (PMC) [22].

Similar to [15] we show that this widely used PMC algorithm fails to provide a reliable estimate of the Spectra. That is, it underestimates (in orders of magnitude) the true quantity of interest. Although there exist good methods for estimating the terminal network reliability, such as Lomonosov’s Turnip [21] and the Splitting method [28], these methods are not suited for the estimation of the network invariants. As was noted in [15] in the context of a PMC algorithm with exponential lifetimes, the reason for the inaccuracy of this scheme lies in the importance of small (rare event) probabilities that cannot be properly estimated via PMC in manageable time.

To overcome this problem, we propose a different sampling scheme, based on the Stochastic Enumeration (SE) method [18]. We show that the SE–based sampling is capable of handling rare–event probabilities while using a relatively small sample size. This will significantly boost our ability to perform an accurate estimation of the Spectra and thus obtain reliable results for the network reliability in the sense of precision and running time. While the SE belongs to the SIS family of algorithms, it is an extension of the well known Knuth’s estimator [29] for approximating the cost of backtrack trees. The main difference between the corresponding Knuth’s estimator and SE is that the latter has a budget parameter \( B \) that limits the number of parallel random walks. We show that this property has a crucial impact on the SE performance. In particular, it turn the SE into a splitting algorithm. It was shown that such splitting mechanisms can introduce a significant variance reduction [30], [31]. For a background on the splitting methods, see [15], [32], [33], [31].

The rest the paper is organized as follows. In Section II we give a short summary of the PMC method and explain why it fails to provide a reliable estimate of the Spectra. In Section III we give an introduction to the SE algorithm and show how the latter can be used to reliably estimate the Spectra. In Section IV we provide numerical evidence for the accuracy of our method. Finally, in Section V we summarize our findings and discuss possible directions for future research.

II. THE PMC METHOD FOR SPECTRA ESTIMATION

We consider a special case of the terminal network reliability problem in which the nodes are completely reliable and all edge failure probabilities are equal; that is, \( q_e = q \) for all \( e \in E \). Additionally, we assume that the edge failures are independent. Under this simplified setting there exists an efficient approach to calculate the terminal network reliability \( r(p) \) or unreliability \( \tau(q) \) — the so–called Spectra method. Moreover, this method can be used for estimating the importance measures of the system; see Appendix A for details. We now briefly describe the Spectra approach.

Let \( e_1, e_2, \ldots, e_m \) be the network edges. Suppose that all of them are initially operational and thus the network is in the UP state, and let \( \pi = (e_{i_1}, \ldots, e_{i_m}) \) be a permutation of edges. Given the permutation \( \pi \), start “erasing” edges (change the edges state from \textit{up} to \textit{down}) moving through the permutation from left to right and check the \textit{UP/DOWN} state of the network after each step. Find the index \( j \) of the first edge \( e_{i_j} \), \( j = 1, \ldots, m \) for which the network switches from \textit{UP} to \textit{DOWN}. This index \( j \) is called the anchor of \( \pi \) and is denoted by \( a(\pi) \).

Next, we assign the uniform distribution on the set of all edge permutations, that is, \( \text{Pr}(\Pi = \pi) = 1/m! \), and define the set

\[
A(k) = \{ \pi: a(\pi) = k \}.
\]

Definition 2.1 (Destruction Spectra [22]): Let \( \Pi \) be a random permutation and define

\[
f_k = \text{Pr}(\Pi \in A(k)) = \frac{|A(k)|}{m!}, \quad k = 0, \ldots, m.
\]

Then,

\[
S_p = \{ f_0, f_1, \ldots, f_m \}
\]

is called the Destruction Spectra, or simply D–Spectra of the network.

Definition 2.2 (Cumulative D–Spectra [22]): The cumulative D–Spectra is defined by

\[
C_{S_p} = \{ F(0), F(1), \ldots, F(m) \},
\]

where

\[
F(k) = \sum_{i=0}^{k} f_i, \quad k = 0, \ldots, m.
\]

The nice feature of the D–Spectra is that once \( C_{S_p} \) is available one can calculate directly the sought network unreliability \( \tau(q) \). Let us define a failure set to be an ordered set of edges such that their failure forces the network to enter the DOWN state and denote by \( N(k) \) the number of network failure sets of size \( k \). Note that each such set is a collection of \( k \) edges whose failure results in the DOWN state of the network. It is readily seen that

\[
N(k) = \binom{m}{k} F(k). \quad (1)
\]

This statement has a simple combinatorial explanation: \( F(k) \) is the fraction of all failure sets of size \( k \) among all subsets of size \( k \) taken from the set of \( m \) components. Note that \( N(k), k = 1, \ldots, m \), is an important system invariant that is of great interest in many applications [26].

Moreover, note that the following holds.

- The network is DOWN if and only if it is in one of its failure sets.
- For fixed \( q \) each failure set of size \( k \) has the probability \( q^k (1-q)^{m-k} \).

Combining this with (1) we obtain
As an anchor of the network enters the DOWN state, next, by specifying the set
\[ A'(k) = \{ \pi | a'(\pi) = k \}, \]
the Construction Spectra (C–Spectra) \( S'_p \) and the Cumulative C–Spectra \( C'_{S'_p} \) can be defined similarly to Definitions 2.1 and 2.2.

Definition 2.3 (Construction Spectra [22]): Let \( \Pi \) be a random permutation and define
\[ f'_k = \mathbb{P} (\Pi \in A'(k)) = \frac{|A'(k)|}{m!}, \quad k = 0, \ldots, m. \]
Then,
\[ S'_p = \{ f'_0, f'_1, \ldots, f'_m \} \]
is called the Construction Spectra, or simply C–Spectra of the network.

Definition 2.4 (Cumulative Construction Spectra [22]): The cumulative C–Spectra is defined by
\[ C'_{S'_p} = \{ F'(0), F'(1), \ldots, F'(m) \}, \]
where
\[ F'(k) = \sum_{i=0}^{k} f'_i, \quad k = 0, \ldots, m. \]

Given the Construction Spectra the network UP probability is given by
\[ r(p) = \sum_{k=0}^{m} \binom{m}{k} p^k (1-p)^{m-k} = \sum_{k=0}^{m} N'(k) p^k (1-p)^{m-k}, \]
where
\[ N'(k) = \binom{m}{k} F'(k). \]
Intuitively, both the destruction and the construction Spectra seems to share similar behavior; Proposition 2.1 establishes their equivalence.

Proposition 2.1 (Construction and Destruction Spectra equivalence): For the Construction and Destruction Spectra, it holds that
\[ f_k = f'_{m-k} \quad \text{for all} \ k = 0, \ldots, m. \]

Proof: Let \( \pi = (e_{i_1}, \ldots, e_{i_m}) \) be a permutation of edges and define the reverse permutation \( \pi^r \) as \( \pi^r = (e_{i_m}, \ldots, e_{i_1}) \). Suppose that \( \pi \in A(k) \), that is \( a(\pi) = k \) for any \( k = 0, \ldots, m \). Note that for this particular \( \pi \) the following holds.
- If the edges \( e_{i_1}, \ldots, e_{i_k} \) and \( e_{i_{k+1}}, \ldots, e_{i_m} \) are in down and up states respectively, the network is DOWN.
- If the edges \( e_{i_1}, \ldots, e_{i_{k-1}} \) and \( e_{i_k}, \ldots, e_{i_m} \) are in down and up states, the network is in UP state.
From this, $a'(\pi^r) = m - k$, that is $\pi^r \in A'(m-k)$. Hence, $\pi \in A(k) \Rightarrow \pi^r \in A'(m-k)$, and we conclude that $|A(k)| = |A'(m-k)|$, so, combining this with Definitions 2.1 and 2.3 the proof is completed by

$$f_k = \frac{|A(k)|}{m!} = \frac{|A'(m-k)|}{m!} = f'_m - k.$$

As an immediate consequence of Proposition 2.1, note that we can freely choose the Construction or the Destruction Spectra to work with and that this particular choice should be guided only by one’s convenience. The above statement is summarized in Corollary 2.1.

**Corollary 2.1:** For any network with $m$ edges, the D–Spectra can be transformed to C–Spectra and vice versa using the formula

$$f_k = f'_m - k \quad \text{for all} \quad k = 0, \ldots, m.$$

Unfortunately, both the construction and the destruction Spectra are generally not available analytically and as consequence a Monte Carlo procedure should be applied. One of the widely adopted approaches, the PMC, is presented in Algorithm 2.1.

**Algorithm 2.1 (PMC Algorithm):** Given a graph $G(V, E, K)$ such that $|E| = m$ and a sample size $N$, execute the following steps.

1) **Step 1 (Initialization):** Set

$$S_p = \{\tilde{f}_0, \ldots, \tilde{f}_m\} \leftarrow \{0, 0, \ldots, 0\}.$$

2) **Step 2 (Main loop):** Repeat $N$ times.

a) $\Pi \leftarrow (e_1, \ldots, e_{im})$ (generate a random edge permutation).

b) $k \leftarrow a(\Pi)$ (find the anchor).

c) $\tilde{f}_k \leftarrow f_k + 1$.

3) **Step 3 (Calculate D–Spectra):**

$$\tilde{f}_k \leftarrow \frac{\tilde{f}_k}{N} \quad \text{for} \quad k = 0, \ldots, m.$$

4) **Step 3 (Calculate Cumulative D–Spectra):**

$$F(k) \leftarrow \sum_{i=0}^{k} \tilde{f}_i \quad \text{for} \quad k = 0, \ldots, m.$$

Let us turn our attention to the Spectra estimation under rare–event settings and consider the artificial Spectra in Table II. The left part of the table presents the “real” Spectra values ($C_{S_p}$) and the right stands for their (fake) “estimates” ($\tilde{C}_{S_p}$). Suppose that $\tilde{C}_{S_p}$ was obtained using Algorithm 2.1. (We deliberately set the “estimates” to be equal to the real values in order to stress the importance of the rare components ($F(4), F(5)$ and $F(6)$))

Note that the proposed Monte Carlo Algorithm 2.1 will not be able to estimate the left part of the Spectra ($F(4), F(5)$ and $F(6)$) in a reliable manner using any manageable sample size, say $N = 10^7$. This problem is due to the well-known issue of Crude Monte Carlo algorithms under rare–event settings. For example, consider the value of $F_4$. Having in mind that $\operatorname{Pr}(a(\pi) = 4) = f_4 = 10^{-12}$, the relative error (RE) [34] of the PMC Algorithm 2.1 for the $f_4$ is given by

$$\text{RE} = \sqrt{\frac{\text{Var}(\tilde{f}_4)}{\mathbb{E}(\tilde{f}_4)^2 N}} = \sqrt{\frac{f_4(1-f_4)}{f_4^2 N}} \approx 10^6/\sqrt{N},$$

where $N$ is the sample size. The above equation suggests that in order to achieve even a modest (say 10%) RE, the value of $N$ should be huge.

Applying (2) to the Spectra values from Table II, we get the corresponding network reliability estimations. Table III summarizes the values for the obtained estimators $\tilde{\pi}(q)$ and $\tilde{\tau}(q)$ using the exact and the approximated Spectra respectively.

One can easily note that the right column of Table III is a clear underestimation for $q \leq 10^{-4}$. A more careful observation of the results reveals the importance of the leftmost values of Spectra. Note that $F(4), F(5)$ and $F(6)$ were “evaluated” to zero, and, for $q \leq 10^{-4}$, (2) accumulates most of its mass.
for $k = 4, 5, 6$. For example, if we examine $q = 10^{-4}$ and evaluate (2) for $k = 0, \ldots, 6$, we get

$$\sum_{k=0}^{6} \binom{19}{k} F(k)(10^{-4})^k (1 - 10^{-4})^{19-k} \approx 3.989017 \cdot 10^{-25},$$

which is almost equal to the true probability

$$\tau(10^{-4}) = \sum_{k=0}^{19} \binom{19}{k} F(k)(10^{-4})^k (1 - 10^{-4})^{19-k} \approx 3.989067 \cdot 10^{-25}.$$

Clearly, the remaining probability mass

$$\sum_{k=7}^{19} \binom{19}{k} F(k)(10^{-4})^k (1 - 10^{-4})^{19-k} \approx 5 \cdot 10^{-30}$$

forms the value of $\tau(10^{-4})$ because $F(k) = F(k)$ for $k = 7, \ldots, 19$.

We shall summarize the above discussion as follows. For highly reliable networks (that is, networks with small edge failure probabilities $q$), Algorithm 2.1 fails to produce reliable results because it requires calculations that involve the accurate estimation of rare-event probabilities; see also [15] for a similar discussion regarding the PMC and Turnip with exponential lifetimes. In other words, in the rare–event setting, the system invariant (Spectra) cannot be accurately estimated using Algorithm 2.1. Naturally, this inaccurate estimation also causes the importance measures to be corrupted. We will use network reliability examples to demonstrate the accuracy of the estimated Spectra components. To overcome the problem of rare events we propose to adopt the SE algorithm that is described in the next section.

III. Stochastic Enumeration Method for Counting Trees

In this section we provide a brief overview of the SE method for counting trees. The algorithm is an extension of the one introduced in [31]. Our setting is as follows. Consider a rooted tree $T = (V, E)$ with node set $V$ and edge set $E$ (so that $|E| = |V| - 1$). We denote the root of the tree by $v_0$, and for any $v \in V$ the subtree rooted at $v$ is denoted by $T_v$. With each node $v$ is associated a nonnegative cost $c(v)$. The main quantity of interest is the total cost of the tree,

$$\text{Cost}(T) = \sum_{v \in V} c(v)$$

or, more generally, the total cost of a subtree $T_v$ --- denoted by $\text{Cost}(T_v)$. For each node $v$ we denote the set of successors of $v$ by $S(v)$.

Definition 3.1 (Hyper nodes and forests): Let $\{v_1, \ldots, v_r\} \in V$ be tree nodes.

- We call a collection of distinct nodes in the same level of the tree $v = \{v_1, \ldots, v_r\}$ a hyper node of cardinality $|v| = r$.
- Let $v$ be a hyper node. Generalizing the tree node cost, we define the cost of the hyper node as

$$c(v) = \sum_{v' \in v} c(v').$$

- Let $v$ be a hyper node. Define the set of successors of $v$ as

$$S(v) = \bigcup_{v' \in v} S(v').$$

- Let $v$ be a hyper node and let $B \in \mathbb{N}, B \geq 1$. Define

$$H(v) = \begin{cases} \{S(v)\} & \text{if } |S(v)| \leq B \\ \{w \mid w \subseteq S(v), |w| = B\} & \text{if } |S(v)| > B, \end{cases}$$

be the set of all possible hyper nodes having cardinality $\max\{|B, |S(v)|\}$ that can be formed from the set of $v$’s successors. Note that if $|S(v)| \leq B$, we get a single hyper node with cardinality $|S(v)|$.

For each hyper node $v$ let

$$T_v = \bigcup_{v \in v} T_v$$

be the forest of trees rooted at $v$. See Figure 2 for an example of hyper node $v = \{v_1, v_2, v_3, v_4\}$ and its corresponding forest $T_v = \{T_{v_1}, T_{v_2}, T_{v_3}, T_{v_4}\}$.

For each forest rooted at hyper node $v$, define its total cost as

$$\text{Cost}(T_v) = \sum_{v \in v} \text{Cost}(T_v).$$

With these definitions in hand we are ready to state the main SE algorithm.

Algorithm 3.1 (Stochastic Enumeration Algorithm): Given a forest $T_v$ of height $h$ rooted at a hyper node $v$, and a budget $B \geq 1$, execute the following steps.

1. Step 1 (Initialization): Set $k \leftarrow 0$, $D \leftarrow 1$, $X_0 = v$ and $C_{SE} \leftarrow c(X_0)/|X_0|$.
2. Step 2 (Compute the successors): Let $S(X_k)$ be the set of all children of $X_k$.
3. Step 3 (Terminal position?): If $|S(X_k)| = 0$, the algorithm stops, returning $|v|C_{SE}$ as an estimator of $\text{Cost}(T_v)$.
4. Step 4 (Advance): Choose hyper node $X_{k+1} \in H(X_k)$ at random, each choice being equally likely. (Thus, each choice occurs with probability $1/|H(X_k)|$.) Set $D_k = |S(X_k)|$ and $D \leftarrow D_kD$, then set $C_{SE} \leftarrow$

![Fig. 2. Hyper node $v$ that contains regular tree nodes $v_1, v_2, v_3$ and $v_4$ with their corresponding subtrees.](image-url)
that the cost of all vertices is zero except for $v$. The latter can bring enormous variance reduction, [11], [14], and in the last step of Algorithm 3.1.

It can be shown that the output of Algorithm 3.1 is a random variable

$$C_{SE} = \frac{c(X_0)}{|X_0|} + \frac{S(X_0)}{|X_0|} \frac{c(X_1)}{|X_1|} + \cdots + \left( \prod_{0 \leq j \leq k-1} \frac{|S(X_j)|}{|X_j|} \right) \frac{c(X_k)}{|X_k|},$$

where $\tau \leq h$ is the random variable that represents the length of the random walk. The term

$$\left( \prod_{0 \leq j \leq k-1} \frac{|S(X_j)|}{|X_j|} \right) \frac{c(X_k)}{|X_k|} = D \frac{c(X_k)}{|X_k|},$$

which is calculated at Step 4 of Algorithm 3.1 is the estimator for the total cost of the vertices at tree level $k$. Moreover, this estimator is unbiased; that is, for a tree $T$ rooted at $v_0$, and for $v_0 = \{v_0\}$,

$$E(C_{SE}(T_{v_0})) = \text{Cost}(T).$$

For the proof of unbiasedness and for typical run of Algorithm 3.1, see Appendices B and C respectively.

Note that (3) represents the sum of unbiased estimators to the costs of tree levels at heights $k = 0, \ldots, h$. With this observation in hand one can introduce a simple modification of Algorithm 3.1 such that instead of the entire tree cost, the algorithm will return separate estimators for each level. All we need to do is to replace the single random variable $C_{SE}$ with $h$ variables $C_{SE}^{(0)}, \ldots, C_{SE}^{(h)}$, and substitute the expression $C_{SE} \leftarrow C_{SE} + \left( \frac{c(X_{k+1})}{|X_{k+1}|} \right) D$ with $C_{SE}^{(k+1)} \leftarrow C_{SE}^{(k)} + \left( \frac{c(X_{k+1})}{|X_{k+1}|} \right) D$ in the last step of Algorithm 3.1.

Next, we concentrate on the crucial property of the SE algorithm — the built-in splitting mechanism.

A. SE Splitting mechanism

The SE algorithm possesses a built-in splitting mechanism. The latter can bring enormous variance reduction, [11], [14], [32], [31].

Consider the “hair brush” tree $T$ in Figure 3 and suppose that the cost of all vertices is zero except for $v_{n+1}$, which has a cost of unity. Our goal is to estimate the cost of this tree, which obviously satisfies

$$\text{Cost}(T) = 1.$$

It will become clear from the following discussion that the budget parameter $B$ is controlling the SE Algorithm 3.1 splitting capability. We will consider two cases. In particular we examine the behavior of the SE Algorithm 3.1 with budgets $B = 1$ and $B = 2$ respectively.

- If we set $B = 1$, the SE Algorithm 3.1 essentially adopts the behaviour of Knuth’s estimator, [29]. Note that in this case the algorithm reaches the vertex of interest, $v_{n+1}$, with probability $1/2^n$ and with $D = 2^n$. In all other cases, the algorithm terminates with some $D'$ and a zero cost node $\bar{v}_i$, $i = 2, \ldots, n + 1$. It follows that the expectation and variance of the corresponding SE estimator are

$$E(C_{SE}) = \frac{1}{2^n} \cdot 2^n + \frac{2^n - 1}{2^n} \cdot D' \cdot 0 = 1,$$

and

$$E(C_{SE}^2) = \frac{1}{2^n} \cdot (2^n \cdot 1)^2 + \frac{2^n - 1}{2^n} \cdot (D' \cdot 0)^2 = 2^n \Rightarrow \Rightarrow \text{Var}(C_{SE}) = E(C_{SE}^2) - E(C_{SE})^2 = 2^n - 1.$$

- On the other hand, setting $B = 2$ will force Algorithm 3.1 to reach $v_{n+1}$ with probability 1. Note that with this budget and for $i = 2, \ldots, n$, one algorithm trajectory, (random walk from the tree root), is always disappearing at $\bar{v}_i$ vertices from the left, but the second one is always split in two new trajectories at the corresponding $v_i$ nodes from the right. Following the execution steps of the SE Algorithm 3.1 one can verify that at the final iteration the cost of the hyper node $X_{n+1} = \{\bar{v}_{n+1}, \ v_{n+1}\}$ is $0 + 1 = 1$, so

$$\frac{c(X_{n+1})}{|X_{n+1}|} = \frac{1}{2}.$$

In addition, the final value of $D$ is

$$D = 2 \cdot \frac{1}{n-1} \text{ times} = 2.$$

It follows that the expectation and variance of the corresponding SE estimator are

$$E(C_{SE}) = 1 \cdot 2 \cdot \frac{1}{2} = 1,$$

and

$$E(C_{SE}^2) = 1 \cdot \left( 2 \cdot \frac{1}{2} \right)^2 = 1 \Rightarrow \Rightarrow \text{Var}(C_{SE}) = E(C_{SE}^2) - E(C_{SE})^2 \cdot 1 - 1 = 0.$$
By increasing the budget $B$ from 1 to 2 we managed to achieve remarkable variance reduction, from $2^n - 1$ to zero.

The above example is the key for understanding the SE splitting mechanism. Note that to deliver some meaningful estimator for the tree cost one needs (at least) to reach the $v_{n+1}$ vertex. In our example, when $B = 1$, this happens with probability $1/2^n$, so we work under the rare–event setting. For the sake of simplicity, let us concentrate on the simple problem of reaching the vertex $v_{n+1}$. Recall that under the Splitting framework, we launch $B$ random walks from the root ($v_1$). Each walk chooses $v_2$ or $\bar{v}_2$ with probability 1/2 respectively; that is, the walks are divided into “good” (those that reach $v_2$) and “bad” (those that reach $\bar{v}_2$). Now, we split the “good” walks such that there will be $B$ of them and continue the process. Note that the following holds.

- The probability of a single walk ($B = 1$) to reach the $v_{n+1}$ vertex is $1/2^n$.
- A careful choice of $B$ (which can be a polynomial in tree height $n$), will allow us to reach the vertex of interest — $v_{n+1}$ with reasonably high probability. In particular, the following holds.

\[
P(\text{The process reaches } v_{i+1} \text{ from } v_i) = 1 - 1/2^B.
\]

\[
P(\text{The process reaches the } v_{n+1} \text{ vertex}) = (1 - 1/2^B)^n.
\]

By choosing (for example) $B = \log_2(n)$,

\[
P(\text{The process reaches the } v_{n+1} \text{ vertex}) \rightarrow e^{-1}, \ n \uparrow \infty.
\]

Clearly, the probability of $e^{-1}$ is much better than $1/2^n$. The SE algorithm shares similar splitting behavior. The “bad” walks become extinct and the “good” ones are split to continue to the next level. The only difference is that SE does not randomly generate next level states but uses the full enumeration procedure in Steps 2 and 4, thus introducing an additional variance reduction.

Clearly, we presented an artificial example but it is also illustrative enough for our purposes. Generally speaking, by increasing the budget (in a reasonable manner), we cannot expect to obtain a zero variance estimator for hard approximation problems, but we do hope to achieve a significant variance reduction.

B. SE for Network Reliability

To start with, consider the set of all edge permutations. With these permutations it is possible to build a tree object that we call the permutation tree, for which each path from the root to a leaf corresponds to some specific permutation $\pi$. For example, consider the simple graph in Figure 1 and the corresponding permutation tree that is presented in Figure 4.

**Remark 3.1:** The exact edge mapping from the leftmost to the rightmost permutation in Figure 4 is as follows.

\[
\{e_1, e_2, e_3, e_4\}, \{e_1, e_2, e_4, e_3\}, \{e_1, e_3, e_2, e_4\}, \{e_1, e_3, e_4, e_2\},
\]

\[
\{e_1, e_4, e_2, e_3\}, \{e_1, e_4, e_3, e_2\}, \{e_2, e_1, e_3, e_4\}, \{e_2, e_1, e_4, e_3\},
\]

\[
\{e_2, e_3, e_1, e_4\}, \{e_2, e_3, e_4, e_1\}, \{e_2, e_4, e_1, e_3\}, \{e_2, e_4, e_3, e_1\},
\]

\[
\{e_3, e_1, e_2, e_4\}, \{e_3, e_1, e_4, e_2\}, \{e_3, e_2, e_1, e_4\}, \{e_3, e_2, e_4, e_1\},
\]

\[
\{e_3, e_4, e_1, e_2\}, \{e_3, e_4, e_2, e_1\}, \{e_4, e_1, e_2, e_3\}, \{e_4, e_1, e_3, e_2\},
\]

\[
\{e_4, e_2, e_1, e_3\}, \{e_4, e_2, e_3, e_1\}, \{e_4, e_3, e_1, e_2\}, \{e_4, e_3, e_2, e_1\}\}
\]

By definition, each path from the root to a leaf corresponds to a unique edge permutation $\pi$ and each black vertex corresponds to this permutation’s anchor, $a(\pi)$. It is not hard to see by following the steps of Algorithm 2.1 that step 2(a) generates a random tree path ($\pi$) and step 2(b) finds the anchor $a(\pi)$ — the black vertex. Recall that by definition,

\[
f_k = \frac{|A(k)|}{m!},
\]

so, we can use Figure 4 to calculate the Spectra. The latter is accomplished as follows. Note that we have 8 anchor vertices at level 2 and each such vertex induces two additional paths to the leaves, so,

\[
f_2 = \frac{8 \cdot 2}{4!} = \frac{2}{3}.
\]

Having in mind that at the third tree level the vertices induce a single path to the leaf and combining this with the fact that we have 8 anchor vertices at this level, we conclude that

\[
f_3 = \frac{8 \cdot 1}{4!} = \frac{1}{3}.
\]

The other Spectra components are equal to zero, so by Definition 2.2,

\[
S_p = \left\{0, 0, \frac{1}{3}, \frac{1}{3}, 0\right\},
\]

that is,

\[
F(0) = 0, \ F(1) = 0, \ F(2) = \frac{2}{3}, \ F(3) = 1, \ F(4) = 1.
\]

With the above Cumulative Spectra we get a full network characterization and the desired unreliability $\pi(q)$ can be calculated for any $q$ using (2).

The above discussion is generalized in Theorem 3.1, which provides the connection between the number of anchor (black) nodes at each tree level and the corresponding Spectra.

**Theorem 3.1 (Spectra as a function of anchor nodes):** Let $T$ be a permutation tree. Then,

\[
f_k = \frac{\text{# of anchor nodes at tree level } k}{\text{total # of nodes at level } k}.
\]
Proof: Suppose that there are \( m \) edges and let \( L(k) \) be the set of anchor nodes at tree level \( k \) and consider the path from the tree root to some \( v \in L(k) \). Clearly, an anchor node cannot appear on this path at level \( j \) such that \( j < k \) or \( j > k \), because in this case \( v \not\in L(k) \), so,
\[
|A(k)| = |L(k)| \cdot (\# \text{ of induced paths from } v \in L(k))
\]
Having in mind that each node at level \( k \) induces
\[
(m - k)(m - (k + 1)) \cdots (m - (m - 1)) = (m - k)!
\]
paths to the leaves, we arrive at
\[
|A(k)| = |L(k)| (m - k)!
\]
Moreover, the total number of (anchor and non–anchor) nodes at tree level \( k \) is equal to
\[
m(m - 1)(m - 2) \cdots (m - k + 1) = \frac{m!}{(m - k)!}
\]
so, from Definition 2.1,
\[
f_k = \frac{|A(k)|}{m!} = \frac{|L(k)| (m - k)!}{m!} = \frac{|L(k)|}{m! (m - k)!} = \frac{\# \text{ of anchor nodes at tree level } k}{\text{total } \# \text{ of nodes at level } k}.
\]
\( \Box \)

All we need to do now is to assign a unit cost to the anchor nodes and a zero cost to the other nodes. Recall Algorithm 3.1 and note that \( C_{SE}^{(k)} \) for \( k = 0, \ldots, m \) is an unbiased estimator to the cost of level \( k \). Then, from Theorem 3.1 the D–Spectra is given by
\[
f_k = \mathbb{E} \left( C_{SE}^{(k)} \right) / \frac{m!}{(m - k)!}.
\]

Theorem 3.1 opens the way for Spectra calculation using the SE sampling scheme. The algorithm to do so may be summarized as follows.

Algorithm 3.2 (SE sampling scheme): Given a graph \( G(V, E, K) \) such that \( |E| = m \), the budget \( B \) and a sample size \( N \), execute the following steps.

1) **Step 1 (SE):** Run the SE Algorithm 3.1 to estimate \( C_{SE}^{(0)} \cdots C_{SE}^{(K)} \).

2) **Step 2 (Estimate Spectra):** Set
\[
\hat{f}_k = C_{SE}^{(k)} / \frac{m!}{(m - k)!} \quad \text{for } k = 0, \ldots, m.
\]

3) **Step 3 (Estimate Cumulative Spectra):**
\[
F(k) \leftarrow \sum_{i=0}^{k} \hat{f}_i \quad \text{for } k = 0, \ldots, m.
\]
\( \Box \)

It is important to note that the same permutation tree is used for both Construction and Destruction Spectra except that the anchor nodes will be placed in different locations according to the adopted construction or the destruction setting respectively. Having this in mind, it follows that Theorem 3.1 is also valid for both D–Spectra and C–Spectra and, as a consequence, Algorithm 3.2 can be executed in both (construction/destruction) modes. If one chooses to calculate the C–Spectra, **Step 2** of Algorithm 3.2 should be written as
\[
\hat{f}_{m-k} = C_{SE}^{(k)} / \frac{m!}{(m - k)!} \quad \text{for } k = 0, \ldots, m.
\]

Finally, recall the reliability estimation complication in the context of the highly reliable networks that we reported in Section II. We showed that the error is due to the PMC estimation problem of very small probabilities in the leftmost parts of the D–Spectra. First of all, note that those problematic components of D–Spectra correspond to the anchor nodes at the upper tree levels \((0, 1, 2, \ldots)\) of the permutation tree (in the destruction setting) or to the lower levels of the tree, \((m, m - 1, m - 2, \ldots)\) (in the construction setting); see Corollary 2.1.

The above discussion and the splitting example gives us a clue of how to use SE for our purposes. The SE’s splitting mechanism is able to sample rare–event anchor nodes in the final tree levels. Having this in mind, we will prefer to work with the C–Spectra and use Corollary 2.1 to obtain the corresponding D–Spectra. In particular, our numerical results in Section IV are obtained using the C–Spectra. An additional technical point that one should be aware of is the structure of the permutation tree. In particular, note that as soon as an anchor node is discovered, its induced paths may readily be ignored. Indeed, there is no point in wasting resources by continuing to explore such permutations. The corresponding truncated permutation tree is presented in Figure 5.

![Fig. 5. The truncated permutation tree.](image)

**IV. NUMERICAL RESULTS**

In this section we present a numerical comparison between the PMC Algorithm 2.1 and the SE Algorithm 3.2 for different models. The results were obtained using an Intel Core i7 machine with 4 GB of RAM.

Recall that the crucial parameter of the SE algorithm is its budget \( B \). Clearly, increasing \( B \) means an inevitable increase in computation effort. Nevertheless, it is not very hard to see that the effort increases linearly in \( B \) since at each tree level we perform \( B \) similar computations. In all our examples we choose \( B = 10 \) and repeat the algorithm for 1000 times. We
found numerically that this parameter selection was sufficient for reliable estimation of the Spectra. Based on numerous experiments with different models, our general advise for choosing the budget is as follows. Start from small budget, say \( B \leq 5 \) and increase it gradually. As soon as the rare–event probability of interest stops to decrease, fix this budget and perform the main experiment. This follows from the fact that the SE tends to underestimate the rare–event probabilities.

**Model 1:** Consider the graph family \( \Psi(k, m) \), \( k \in \mathbb{N}, m \geq 2k \) in Figure 6. Each graph is determined by two numbers \( k \) and \( m \). In particular, this graph has two terminal nodes \( s \) and \( t \), and \( k \) special vertices numbered \( 1, \ldots, k \) such that both \( s \) and \( t \) are connected to each of these vertices. In addition, both terminal vertices are connected to \( m/2 - k \) non–special vertices.

Fig. 6. The \( \Psi(k, m) \) graph with \( m - k + 2 \) vertices and \( m \) edges.

Despite the fact that \( \Psi(k, m) \) is fabricated, it will be useful for our discussion. First of all it is straightforward to calculate the network unreliability. Clearly, the only edges that can cause the terminal disconnection are \( e_{s,1}, \ldots, e_{s,k}, e_{t,1}, \ldots, e_{t,k} \). So, if \( k \) is not very large, say less than 25, the graph unreliability can be obtained by full enumeration of up and down states because one need only to check \( 2^k \) possibilities. An additional nice property is that the \( f_0, \ldots, f_{k-1} \) are zero and

\[
f_k = \mathbb{P}(a(\Pi) = k),
\]

can be calculated analytically. To see this, consider a permutation \( \pi = (e_{i_2}, \ldots, e_{i_m}) \). Clearly, if \( a(\pi) = k \), then \( \{e_{i_2}, \ldots, e_{i_k}\} \) should be a subset of \( \{e_{s,1}, \ldots, e_{s,k}, e_{t,1}, \ldots, e_{t,k}\} \). The latter occurs with probability

\[
\frac{(2^k) k! (m-k)!}{m!}.
\]

And now, given that \( \{e_{i_2}, \ldots, e_{i_k}\} \subset \{e_{s,1}, \ldots, e_{s,k}, e_{t,1}, \ldots, e_{t,k}\} \), we shall decide about the way to pick \( k \) edges such that the terminals will become disconnected. For the first edge there are \( 2k \) possibilities and suppose without loss of generality that we picked \( e_{s,1} \). Now we need to pick the second edge; note that it cannot be \( e_{t,1} \), because if we choose to disconnect it, there is no way to pick additional \( k-2 \) edges to disconnect the terminals. This means that the choice is from \( 2k-2 \) possibilities and so on, so, we end up with

\[
\frac{2k(2k-2) \cdots 2}{(2^k)!}
\]

and arrive at

\[
f_k = \mathbb{P}(a(\pi) = k) = \frac{(2^k) k! (m-k)!}{m!} \cdot \frac{2k(2k-2) \cdots 2}{(2^k) k!} = \frac{(2k(2k-2) \cdots 2) (m-k)!}{m!}.
\]

**Tables IV and V** summarize 10 typical runs of PMC Algorithm 2.1 versus SE Algorithm 3.2 for several \( \Psi(k, m) \) models. We can observe from those tables that PMC is unable to estimate the Spectra value \( f_k \). On the other hand, the SE is not sensitive to this rare–event probability. For the SE Algorithm 3.2, we took a budget \( B = 10 \) and a sample size of \( N = 1000 \). For the PMC Algorithm 2.1, we adjusted the sample size such that the CPU is comparable to the one of SE.

**Note** that for each \( \Psi(k, m) \) model we get the same probability of network failure because they share the same parameter \( k \). In particular, we set \( q = 10^{-4} \) and calculate the exact unreliability via full enumeration. The analytical probability of the failure is \( \pi(10^{-4}) = 1.02 \cdot 10^{-37} \). The analytical \( f_k \) was obtained using (4).

**Model 2:** It is worth noting that PMC is able to deliver accurate estimations for small failure probabilities. The purpose of this example is to demonstrate that one can construct a graph instance such that the Spectra does not have very small components and show that the PMC can estimate it with arbitrary \( q \) values (in particular for \( q \to 0^+ \)).
For this experiment we take the dodecahedron graph, the model that is widely considered for a network reliability examples. We show that the problem is easy in sense that there are no rare events involved; that is, we expect both the PMC and the SE algorithms to report reliable results. We set the terminal set to be $K = \{1, 20\}$.

![Dodecahedron Graph](image)

**Fig. 7.** The dodecahedron graph.

We run the SE algorithm with $N = 1000$ and $B = 10$ and the Spectra Algorithm with $N = 350000$. The running time for both algorithms is about 4.7 seconds. In this example the minimal component has the value $\approx 5 \cdot 10^{-4}$; so, both algorithms deliver excellent performances in a reasonable time. Table VI provides typical values obtained during the algorithm’s execution, and Table VII summarizes the corresponding probability that the network is $DOWN$.

**Model 3:** For our last model we consider the hypercube graph $H_5$. The hypercube graph $H_n$ is a regular graph with $2^n$ vertices and $n2^{n-1}$ edges, [35]. In order to construct a hypercube graph, label every $2^n$ vertices with $n$-bit binary numbers and connect two vertices by an edge whenever the Hamming distance of their labels is 1. We set $K = \{0, 24\}$; that is (00000, 11000) in the binary representation.

We run the SE Algorithm 3.2 with $N = 1000$ and $B = 10$ and the PMC Algorithm 2.1 with $N = 300000$. The running time for both SE and Spectra is 28 seconds. Table VIII provides the estimated network unreliability with both PMC and SE algorithms.

Note the difference in the $DOWN$ probabilities for small values of $q$. We already saw this problem — the PMC Algorithm 2.1 cannot estimate rare–event probabilities, hence, the delivered estimator is an under estimation. Table IX summarizes the first components of the obtained Spectra with PMC and SE algorithms respectively. We do not report $F(0), \ldots, F(3)$, because they were evaluated as zero by full enumeration. With the same procedure, we obtained the exact value of $F(4)$, which is equal to $8.3195 \cdot 10^{-8}$, close (about 7%) to the reported value of $8.93 \cdot 10^{-8}$.
TABLE IX
ESTIMATED SPECTRA COMPONENTS.

<table>
<thead>
<tr>
<th>Algorithm</th>
<th>(F(4))</th>
<th>(F(5))</th>
<th>(F(6))</th>
<th>(F(7))</th>
<th>(F(8))</th>
<th>(F(9))</th>
</tr>
</thead>
<tbody>
<tr>
<td>SE</td>
<td>(8.00 \times 10^{-5})</td>
<td>(4.60 \times 10^{-5})</td>
<td>(1.67 \times 10^{-4})</td>
<td>(4.42 \times 10^{-4})</td>
<td>(6.00 \times 10^{-5})</td>
<td>(2.03 \times 10^{-5})</td>
</tr>
<tr>
<td>PMC</td>
<td>0</td>
<td>0</td>
<td>0</td>
<td>0</td>
<td>(1.00 \times 10^{-5})</td>
<td>(2.67 \times 10^{-5})</td>
</tr>
</tbody>
</table>

TABLE X
PMC RELIABILITY ESTIMATION FOR \(N = 10^8\).

<table>
<thead>
<tr>
<th>(q)</th>
<th>(\bar{r}(q))</th>
<th>(\text{Var}(\bar{r}(q)))</th>
</tr>
</thead>
<tbody>
<tr>
<td>(1.00 \times 10^{-5})</td>
<td>(1.80 \times 10^{-25})</td>
<td>(5.80 \times 10^{-31})</td>
</tr>
<tr>
<td>(1.00 \times 10^{-4})</td>
<td>(1.80 \times 10^{-24})</td>
<td>(5.74 \times 10^{-41})</td>
</tr>
<tr>
<td>(1.00 \times 10^{-3})</td>
<td>(1.81 \times 10^{-15})</td>
<td>(5.18 \times 10^{-31})</td>
</tr>
<tr>
<td>(1.00 \times 10^{-2})</td>
<td>(1.88 \times 10^{-15})</td>
<td>(1.85 \times 10^{-21})</td>
</tr>
<tr>
<td>(1.00 \times 10^{-1})</td>
<td>(2.00 \times 10^{-15})</td>
<td>(2.66 \times 10^{-14})</td>
</tr>
<tr>
<td>(2.00 \times 10^{-2})</td>
<td>(6.60 \times 10^{-13})</td>
<td>(2.81 \times 10^{-12})</td>
</tr>
<tr>
<td>(3.00 \times 10^{-3})</td>
<td>(5.57 \times 10^{-12})</td>
<td>(3.40 \times 10^{-11})</td>
</tr>
<tr>
<td>(4.00 \times 10^{-4})</td>
<td>(2.56 \times 10^{-11})</td>
<td>(9.55 \times 10^{-10})</td>
</tr>
<tr>
<td>(5.00 \times 10^{-5})</td>
<td>(9.48 \times 10^{-10})</td>
<td>(1.20 \times 10^{-9})</td>
</tr>
<tr>
<td>(6.00 \times 10^{-6})</td>
<td>(2.94 \times 10^{-9})</td>
<td>(2.670 \times 10^{-8})</td>
</tr>
<tr>
<td>(7.00 \times 10^{-7})</td>
<td>(6.66 \times 10^{-8})</td>
<td>(9.13 \times 10^{-7})</td>
</tr>
<tr>
<td>(8.00 \times 10^{-8})</td>
<td>(8.66 \times 10^{-7})</td>
<td>(7.21 \times 10^{-6})</td>
</tr>
</tbody>
</table>

Next, we run the PMC algorithm 2.1 with sample sizes \(10^6, 10^7\) and \(10^8\), respectively. It is not surprising that \(N = 10^6\) and \(N = 10^7\) are insufficient to provide a meaningful estimator for the rare–event probability of \(8.3195 \times 10^{-8}\). Table X summarizes the results obtained for \(N = 10^8\). The running time of PMC is about 9000 seconds and the estimated variance for the rare–event probabilities is larger than the one obtained by SE.

V. CONCLUSIONS

In this paper we showed that when using the network signature method (Spectra), a satisfactory estimation of network \(DOWN\) state probability depends on the accurate evaluation of all Spectra components. In particular, the leftmost part of D–Spectra turns out to be critical when dealing with highly reliable networks. We showed that under this setting, the simple PMC algorithm for estimating the network unreliability fails to provide a reliable answer. To successfully overcome this issue we introduced an adaptation of the network sampling scheme for tree cost evaluation — Stochastic Enumeration (SE). Our numerical results indicate that thanks to its built–in splitting mechanism SE is able to successfully work in the rare event environment while using a relatively small sample size. Having in mind that some rare–event estimation problems can be represented as trees, we conjecture that the SE may be viewed as a general powerful technique for rare–event probability estimation and we expect to see its further usage in the future.

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APPENDIX A
IMPORTANCE MEASURES

We present a short introduction for Birnbaum Importance Measure (BIM) [36] and Joint Reliability Importance (JRI) [37] measures. Suppose a system consists of \(n\) independent components, and component \(j\) has reliability \(p_j, j = 1, \ldots, n\). Let the system reliability be

\[
r(p_1, \ldots, p_n).\]

The BIM of component \(j\) is defined by Birnbaum [36] as

\[
BIM_j = \frac{\partial r(p_1, \ldots, p_n)}{\partial p_j}. \tag{5}
\]

The JRI for two components has been introduced by Hong and Lie [37] as a measure of how components interact in determining system reliability. The JRI of components \(i\) and \(j\) is defined as

\[
JRI_{(ij)} = \frac{\partial^2 r(p_1, \ldots, p_n)}{\partial p_i \partial p_j}. \tag{6}
\]

To illustrate the importance of BIM and JRI, suppose that we can increase \(p_j\) by \(\Delta p_j, j = 1, \ldots, n\). Then from the definitions of the partial derivatives (5) and (6), it follows that the following general recommendation can be applied.

1) If a single component is reinforced, the best result is achieved by replacing component \(j\) which has the largest value of \(BIM_j \cdot \Delta p_j\).
2) If two components, \(i\) and \(j\) are subject to the reinforcement, then the total increase of system reliability is

\[
BIM_i \Delta p_i + BIM_j \Delta p_j + JRI_{(ij)} p_i p_j.
\]

The expressions for the BIM and JRI in (5) and (6) are useless in practice since the analytic form of \(r(p_1, \ldots, p_n)\) is not available. This principal difficulty is resolved since we obtain expressions for them by using combinatorial invariant — the Spectra, see [27].

Usually, it is sufficient to consider these functions (derivatives) for \(p_1 = p_2 = \cdots = p_n = p = 1 - q\), see [27] for details. In this case, the component importance measures can be obtained from the network Cumulative Spectra. The connection is as follows. Recall that \(F(k)\) is the probability that the system is \(DOWN\) if \(k\) randomly chosen components are \(DOWN\) (and remaining \(n - k\) are \(UP\)). This probability can be written as

\[
F(k) = F(k; 1_1) + F(k; 0_j),
\]

where \(F(k; 1_j)\) and \(F(k; 0_j)\) stands for the probabilities that the network is \(DOWN\) if \(k\) randomly chosen components are \(DOWN\) and component \(j\) is among non-failed (for \(1_j\)) and failed (for \(0_j\)) components respectively. Similarly, for any two components \(i\) and \(j\), we can write:

\[
F(k) = F(k; 1_i, 1_j) + F(k; 1_i, 0_j) + F(k; 0_i, 1_j) + F(k; 0_i, 0_j).
\]

It was shown in [27] that the following holds.

1) The expression for \(BIM_j\) is given by
BIM_\text{j} = n! \left( \sum_{x=1}^{n} F(x; 0, 0)q^{x-1}p^{n-x}/x!(n-x)! \right)
- \sum_{x=1}^{n} (F(x) - F(x; 1, j))q^{x-1}p^{n-x-1}/x!(n-x)! \right).

2) The expression for JRI_{ij} is given by

JRI_{ij} = n! \left( \sum_{x=1}^{n} F(x; 1, j)q^{x-1}p^{n-x-1}/x!(n-x)! \right)
+ \sum_{x=1}^{n} F(x; 0, 1)q^{x-1}p^{n-x-1}/x!(n-x)!
- \sum_{x=1}^{n} F(x; 0, j)q^{x-2}p^{n-x}/x!(n-x)!
- \sum_{x=1}^{n} F(x; 1, 1)q^{x}p^{n-x-2}/x!(n-x)!.

We conclude this short overview with a crucial observation. Having a Monte Carlo algorithm for estimating the Spectra, one can readily get the estimates for F(k; 1, j), F(k; 0, j), F(k; 1, 1), F(k; 0, 1), and F(k; 0, 0, j), by running the same algorithm while fixing the given components to the appropriate states. For example, to calculate F(k; 0, 1, j), one should (prior to running the algorithm) fix the jth component to down and up states respectively.

**APPENDIX B**

**PROOF OF SE’S UNBIASEDNESS**

To prove the main result we will need the following technical lemma.

**Lemma B.1 (Sum of k-subsets):** Let r_1, \ldots, r_n and u be scalars such that

\[ \forall j = 1, \ldots, n, \; r_j \geq 0 \] and \( u = 1, \ldots, n \), and,

\[ S = \{ s \mid s \subseteq \{ r_1, \ldots, r_n \}, |s| = u \}. \]

Then,

\[ \sum_{s \in S} \frac{\sum_{r \in S} r}{u} \frac{\binom{n}{u}}{n} \sum_{1 \leq j \leq n} r_j \]

holds.

**Proof:** Note that there are exactly \( \binom{n-1}{u-1} \) subsets in which each \( r_j \) (\( j = 1, \ldots, n \)) appears. We conclude the proof with

\[ \sum_{s \in S} \frac{\sum_{r \in S} r}{u} \frac{\binom{n-1}{u-1}}{u} \sum_{1 \leq j \leq n} r_j = \frac{n!}{u!(n-u)!} \sum_{1 \leq j \leq n} r_j = \frac{n!}{n} \sum_{1 \leq j \leq n} r_j = \frac{1}{u} \sum_{1 \leq j \leq n} r_j. \]

Recall from Definition 3.1 that for any hyper node v, T_v denotes the forest rooted at v, and that its cost is \( \text{Cost}(T_v) \).

Let \( |v| \text{Cost}_\text{SE}(T_v) \) be the corresponding estimator, as returned by Algorithm 3.1. The following theorem shows that this estimator is unbiased.

**Theorem B.1 (Unbiased Estimator):** Let v be a hyper node and let \( H(S(v)) = \{ \text{w}_1, \ldots, \text{w}_d \} \) be its set of hyper children. Then,

\[ \mathbb{E}(\text{Cost}_\text{SE}(T_v)) = \frac{\text{Cost}(T_v)}{|v|}. \]

**Proof:** By the recursive structure of Algorithm 3.1, we have

\[ \text{Cost}_\text{SE}(T_v) = \frac{c(v)}{|v|} + \frac{|S(v)|}{|v|} \text{Cost}_\text{SE}(T_w), \]

where \( W \) is a hyperchild of v selected uniformly at random from \( H(S(v)). \) To show (7) we proceed by induction on the tree height.

* h = 0:

\[ \mathbb{E}(\text{Cost}_\text{SE}(T_v)) = \mathbb{E} \left( \frac{c(v)}{|v|} + \frac{|S(v)|}{|v|} \cdot 0 \right) = \frac{c(v)}{|v|} + \frac{|S(v)|}{|v|} \cdot 0 = \frac{\text{Cost}(T_v)}{|v|}. \]

* Suppose that the proposition is correct for heights \( 0, \ldots, h - 1 \). Combining this with (8) we get

\[ \mathbb{E}(\text{Cost}_\text{SE}(T_v)) = \mathbb{E} \left( \frac{c(v)}{|v|} + \frac{|S(v)|}{|v|} \text{Cost}_\text{SE}(T_w) \right) \]

Consider now the following two cases.

1) \( |S(v)| \leq B \). Hence, \( H(S(v)) = \{ \text{w}_1 \} \), \( |S(v)| = |\text{w}_1| \), and \( d = 1 \), so that

\[ \frac{c(v)}{|v|} + \frac{|S(v)|}{|v|} \left( \frac{1}{d} \sum_{1 \leq j \leq d} \text{Cost}(T_{w_j}) \right) = \frac{c(v)}{|v|} + \frac{|S(v)|}{|v|} \text{Cost}(T_{w_1}) = \frac{\text{Cost}(T_v)}{|v|}. \]

2) \( |S(v)| > B \). In this case, there is a set of possible hyper nodes that will be chosen uniformly at random from \( H(S(v)). \) So, \( H(S(v)) = \{ \text{w}_1, \ldots, \text{w}_d \} \),

\[ d = |H(S(v))| = \binom{|S(v)|}{B} > 1 \] and \( |w_j| = \]
for all $j = 1, \ldots, d$. We continue with

$$\frac{c(v)}{|v|} + \frac{|S(v)|}{|v|} \left( 1 - \frac{1}{d} \sum_{1 \leq j \leq c_{Bv}} \frac{\text{Cost}(T_{w_j})}{|w_j|} \right) = \frac{c(v)}{|v|} + \frac{|S(v)|}{|v|} \left( \left( \frac{|S(v)|}{B} \right)^{-1} \sum_{1 \leq j \leq d} \frac{\text{Cost}(T_{w_j})}{B} \right)$$

$$= \frac{c(v)}{|v|} + \frac{|S(v)|}{|v|} \left( \left( \frac{|S(v)|}{B} \right)^{-1} \sum_{1 \leq j \leq d} \sum_{w \in w_j} \text{Cost}(T_w) \right)$$

$$= \frac{c(v)}{|v|} + \frac{|S(v)|}{|v|} \left( \left( \frac{|S(v)|}{B} \right)^{-1} \sum_{w \in S(v)} \text{Cost}(T_w) \right)$$

$$= \frac{c(v)}{|v|} + \frac{|S(v)|}{|v|} \left( \left( \frac{|S(v)|}{B} \right)^{-1} \sum_{w \in S(v)} \text{Cost}(T_w) \right)$$

$$= \frac{c(v)}{|v|} + \frac{|S(v)|}{|v|} \left( \frac{\text{Cost}(T_{S(v)})}{|S(v)|} \right)$$

$$= \frac{c(v) + \text{Cost}(T_{S(v)})}{|v|} = \frac{\text{Cost}(T_{v_0})}{|v|}.$$  

If for the original tree $T$ with root $v_0$ we define $v_0 = \{v_0\}$, then the forest $T_{v_0}$ is identical to $T$ and, with $|v_0| = 1$, Theorem B.1 yields the following corollary.

**Corollary B.1 (Unbiased tree estimator):** Let $T$ be a tree rooted at $v_0$, and let $v_0 = \{v_0\}$. Then, SE returns unbiased estimator for the total tree cost; that is,

$$\mathbb{E}(C_{SE}(T_{v_0})) = \text{Cost}(T).$$

**APPENDIX C**

**SE example**

We consider an example run of the SE Algorithm 3.1 while using different budget sizes. The SE algorithm does not operate on the original tree but rather on the associate “hyper tree”. This crucial property (what we call tree folding) may lead to significant variance reduction. One should also note that the corresponding “tree folding” property is a direct consequence of the built-in splitting mechanism of the SE, see the discussion in Section III-A.

Consider a tree $T$ displayed in Figure 8. Suppose that we wish to count the number of nodes, so $c(v) = 1$ for all $v \in T$.

1) For $B = 1$, each run of Algorithm 3.1 will choose one of possible 5 paths. Below, we consider all the paths, the obtained estimator and the corresponding probabilities.

a) $1 - 2, C_{SE} = 1 + 3 = 4$, with probability $1/3$.

b) $1 - 4 - 7 - 11, C_{SE} = 1 + 3 + 3 + 3 = 10$, with probability $1/3$.

c) $1 - 3 - 5 - 8, C_{SE} = 1 + 3 + 6 + 6 = 16$, with probability $1/3 \cdot 1/2 = 1/6$.

d) $1 - 3 - 6 - 9, C_{SE} = 1 + 3 + 6 + 12 = 22$, with probability $1/3 \cdot 1/2 \cdot 1/2 = 1/12$.

e) $1 - 3 - 6 - 10, C_{SE} = 1 + 3 + 6 + 12 = 22$, with probability $1/3 \cdot 1/2 \cdot 1/2 = 1/12$.

It is easy to check that

$$\mathbb{E}(C_{SE}(T_{v_0})) = 4 \cdot 1/3 + 10 \cdot 1/3 + 16 \cdot 1/6 + 22 \cdot 1/12 + 22 \cdot 1/12 = 11,$$

and that

$$\mathbb{E}(C_{SE}^2(T_{v_0})) = 4^2 \cdot 1/3 + 10^2 \cdot 1/3 + 16^2 \cdot 1/6 + 22^2 \cdot 1/12 + 22^2 \cdot 1/12 = 162 \Rightarrow$$

$$\Rightarrow \text{Var}(C_{SE}) = \mathbb{E}(C_{SE}^2) - \mathbb{E}(C_{SE})^2 = 162 - 11^2 = 41.$$

2) For $B = 2$ the SE algorithm starts at the root and finds that there are 3 child nodes, see Figure 9. Recall that $B = 2$, so, we set $C_{SE} \leftarrow 1$ and $D \leftarrow 3$ and continue to one of the child hyper nodes $(\{2, 3\}, \{2, 4\}$ or $\{2, 3\})$. The process continues until reaching the leaves. Note that near each hyper node $X$ we write its average degree, $|S(X)|/|X|$, inside the brackets. For example, the hyper node $\{1\}$ has an average degree of $3/1$ and the hyper node $\{2, 4\}$ has an average degree of $1/2$, because in the original tree the degree of node 2 is zero and the degree of node 4 is 1, respectively. The folded tree in Figure 9 corresponds to the SE algorithm with $B = 2$. Each run of Algorithm 3.1 will also choose one of possible 5 paths. Below, we consider all the paths, the obtained estimator and the corresponding probabilities.

a) $\{1\} - \{2, 3\} - \{5, 6\}, C_{SE} = 1 + 3 + 3 \cdot 1 + 3 \cdot 3/2 = 11.5$, with probability $1/3$.

b) $\{1\} - \{2, 4\} - \{7\}, C_{SE} = 1 + 3 + 3 \cdot 1/2 + 3 \cdot 1/2 = 7$, with probability $1/3$. 

Fig. 8. A tree with 11 nodes.

Fig. 9. A folded tree.
Fig. 9. SE folded tree for \( B = 2 \).

c) \( \{1\} - \{3, 4\} - \{5, 6\}, C_{SE} = 1 + 3 + 3 \cdot 3/2 + 9/2 \cdot 3/2 = 15.25 \), with probability \( 1/9 \).
d) \( \{1\} - \{3, 4\} - \{5, 7\}, C_{SE} = 1 + 3 + 3 \cdot 3/2 + 9/2 \cdot 1 = 13 \), with probability \( 1/9 \).
e) \( \{1\} - \{3, 4\} - \{6, 7\}, C_{SE} = 1 + 3 \cdot 3/2 + 9/2 \cdot 3/2 = 15.25 \), with probability \( 1/9 \).

It is easy to check that

\[
\mathbb{E}(C_{SE}) = 11.5 \cdot 1/3 + 7 \cdot 1/3 + 15.25 \cdot 2/9 + 22 \cdot 1/12 + 13 \cdot 1/9 = 11,
\]

and that

\[
\mathbb{E}(C_{SE}^2) = 11.5^2 \cdot 1/3 + 7^2 \cdot 1/3 + 15.25^2 \cdot 2/9 + 22 \cdot 1/12 + 13^2 \cdot 1/9 = 130.875 \Rightarrow
\]

\[
\Rightarrow \text{Var}(C_{SE}) = \mathbb{E}(C_{SE}^2) - \mathbb{E}(C_{SE})^2 = 130.875 - 11^2 = 9.875.
\]

This example illustrates the power of the SE tree folding. Recall that the variance for the \( B = 1 \) case was equal to \( 41 \), but, despite of the fact that the budget of SE is only twice as compared to the previous case, \( (1) \), the SE estimator has a variance of \( 9.875 \), hence, we obtained factor 4 variance reduction.

3) For \( B = 3 \) there is no tree level such that the number of nodes in it is greater than \( B \), so the original tree collapses to a trivial hyper tree where all the hyper node degrees are equal to 1. This will immediately result in a zero variance estimator. Consider the folded tree in Figure 10 that corresponds to the SE algorithm with \( B = 3 \).

Algorithm 3.1 will find a single path \( \{1\} - \{2, 3, 4\} - \{5, 6, 7\} \), (with probability 1), such that

\[
C_{SE} = 1 + 3 \cdot 1 + 3 + 3 \cdot 1 + 3 \cdot 4/3 = 11
\]

which results in a zero variance estimator.

REFERENCES


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