# A Spatially Structured Metapopulation Model with Environmental Influence

### Andrew Smith

Australia New Zealand Applied Probability Workshop University of Queensland

### July 10, 2013



AUSTRALIAN RESEARCH COUNCIL Centre of Excellence for Mathematics and Statistics of Complex Systems



AUSTRALIA

### Populations that occupy geographically distinct locations.

- Individuals reside on patches and can migrate to other patches.
- When an individual migrates to an empty patch, they colonise it.
- Patches can become extinct when no individuals are left.
- If we only count the number of occupied patches, then the metapopulation could be modelled by a stochastic logistic model.
- However, we will be counting the number of individuals on each patch.

- Populations that occupy geographically distinct locations.
- Individuals reside on patches and can migrate to other patches.
- When an individual migrates to an empty patch, they colonise it.
- Patches can become extinct when no individuals are left.
- If we only count the number of occupied patches, then the metapopulation could be modelled by a stochastic logistic model.
- However, we will be counting the number of individuals on each patch.

- Populations that occupy geographically distinct locations.
- Individuals reside on patches and can migrate to other patches.
- When an individual migrates to an empty patch, they colonise it.
- Patches can become extinct when no individuals are left.
- If we only count the number of occupied patches, then the metapopulation could be modelled by a stochastic logistic model.
- However, we will be counting the number of individuals on each patch.

- Populations that occupy geographically distinct locations.
- Individuals reside on patches and can migrate to other patches.
- When an individual migrates to an empty patch, they colonise it.
- Patches can become extinct when no individuals are left.
- If we only count the number of occupied patches, then the metapopulation could be modelled by a stochastic logistic model.
- However, we will be counting the number of individuals on each patch.

- Populations that occupy geographically distinct locations.
- Individuals reside on patches and can migrate to other patches.
- When an individual migrates to an empty patch, they colonise it.
- Patches can become extinct when no individuals are left.
- If we only count the number of occupied patches, then the metapopulation could be modelled by a stochastic logistic model.
- However, we will be counting the number of individuals on each patch.

- Populations that occupy geographically distinct locations.
- Individuals reside on patches and can migrate to other patches.
- When an individual migrates to an empty patch, they colonise it.
- Patches can become extinct when no individuals are left.
- If we only count the number of occupied patches, then the metapopulation could be modelled by a stochastic logistic model.
- However, we will be counting the number of individuals on each patch.

### **Structured Metapopulation Models**

- Our model is an example of Kingman's <sup>1</sup> Markov population process.
- Define *J* to be the number of patches in the metapopulation and  $n_i(t)$  as the number of individuals occupying patch *i* at time *t*.
- The Markov process (n(t), t ≥ 0) describing the state of the metapopulation takes values in

 $S_N = \{0,\ldots,N_1\} \times \cdots \times \{0,\ldots,N_J\}.$ 

• The only nonzero transition rates are given by

$$q(n, n + e_i) = n_i b_i \left(\frac{n_i}{N_i}\right),$$
  

$$q(n, n - e_i) = \phi_i n_i \lambda_{i0} + d_i n_i,$$
  

$$q(n, n - e_i + e_j) = \phi_i n_i \lambda_{ij} \frac{N_j - n_j}{N_i} \text{ for all } j \neq i.$$

<sup>&</sup>lt;sup>1</sup> J. F. C. Kingman, Markov population processes, Journal of Applied Probability 6 (1969) 1–18.

- Our model is an example of Kingman's <sup>1</sup> Markov population process.
- Define *J* to be the number of patches in the metapopulation and  $n_i(t)$  as the number of individuals occupying patch *i* at time *t*.

### The Markov process (n(t), t ≥ 0) describing the state of the metapopulation takes values in

 $S_N = \{0,\ldots,N_1\} \times \cdots \times \{0,\ldots,N_J\}.$ 

• The only nonzero transition rates are given by

$$q(n, n + e_i) = n_i b_i \left(\frac{n_i}{N_i}\right),$$
  

$$q(n, n - e_i) = \phi_i n_i \lambda_{i0} + d_i n_i,$$
  

$$q(n, n - e_i + e_j) = \phi_i n_i \lambda_{ij} \frac{N_j - n_j}{N_i} \text{ for all } j \neq i.$$

<sup>&</sup>lt;sup>1</sup> J. F. C. Kingman, Markov population processes, Journal of Applied Probability 6 (1969) 1–18.

- Our model is an example of Kingman's <sup>1</sup> Markov population process.
- Define *J* to be the number of patches in the metapopulation and  $n_i(t)$  as the number of individuals occupying patch *i* at time *t*.
- The Markov process (n(t), t ≥ 0) describing the state of the metapopulation takes values in

$$S_N = \{0, \ldots, N_1\} \times \cdots \times \{0, \ldots, N_J\}.$$

The only nonzero transition rates are given by

$$\begin{aligned} q(n, n + e_i) &= n_i b_i \left(\frac{n_i}{N_i}\right), \\ q(n, n - e_i) &= \phi_i n_i \lambda_{i0} + d_i n_i, \\ q(n, n - e_i + e_j) &= \phi_i n_i \lambda_{ij} \frac{N_j - n_j}{N_i} \quad \text{for all } j \neq i. \end{aligned}$$

<sup>&</sup>lt;sup>1</sup> J. F. C. Kingman, Markov population processes, Journal of Applied Probability 6 (1969) 1–18.

- Our model is an example of Kingman's <sup>1</sup> Markov population process.
- Define *J* to be the number of patches in the metapopulation and  $n_i(t)$  as the number of individuals occupying patch *i* at time *t*.
- The Markov process (n(t), t ≥ 0) describing the state of the metapopulation takes values in

 $\mathcal{S}_N = \{0, \ldots, N_1\} \times \cdots \times \{0, \ldots, N_J\}.$ 

• The only nonzero transition rates are given by

$$\begin{aligned} q(n, n + e_i) &= n_i b_i \left(\frac{n_i}{N_i}\right), \\ q(n, n - e_i) &= \phi_i n_i \lambda_{i0} + d_i n_i, \\ q(n, n - e_i + e_j) &= \phi_i n_i \lambda_{ij} \frac{N_j - n_j}{N_j} \quad \text{for all } j \neq i. \end{aligned}$$

<sup>&</sup>lt;sup>1</sup> J. F. C. Kingman, Markov population processes, Journal of Applied Probability 6 (1969) 1–18.



### Diagram



Model

### Diagram



## Assumptions

### We assume

(1) 
$$\frac{N_i}{N} \to M_i$$
 as  $N \to \infty$ , where  $N = \sum_j N_j$ .

### (II) The birth function *b<sub>i</sub>* is

- Lipschitz,
- strictly decreasing on [0, 1],
- $b_i(x) = 0$  for all  $x \ge 1$  and
- xb<sub>i</sub>(x) is strictly concave on [0, 1].

# Assumptions

We assume

(I) 
$$\frac{N_i}{N} \to M_i$$
 as  $N \to \infty$ , where  $N = \sum_j N_j$ .

(II) The birth function  $b_i$  is

- Lipschitz,
- strictly decreasing on [0, 1],
- $b_i(x) = 0$  for all  $x \ge 1$  and
- *xb<sub>i</sub>*(*x*) is strictly concave on [0, 1].

# Deterministic Limit

### Theorem

If  $\lim_{N\to\infty} n(0)/N = x_0$ , then, for every s > 0 and  $\delta > 0$ ,

$$\lim_{N\to\infty} \Pr\left(\sup_{t\leq s} \left|\frac{n(t)}{N} - x(t,x_0)\right| > \delta\right) = 0.$$

where  $x(t, x_0)$  is the solution to

$$\frac{dx(t)}{dt}=F(x),\quad x(0)=x_0,$$

with

$$\begin{aligned} \mathsf{F}_{i}(\mathbf{x}) &= \left( \mathsf{b}_{i} \left( \frac{\mathbf{x}_{i}}{\mathbf{M}_{i}} \right) - \mathsf{d}_{i} - \phi_{i} \right) \mathbf{x}_{i} \\ &+ \sum_{j \neq i} \left( \phi_{j} \mathbf{x}_{j} \lambda_{ji} + \left( \phi_{i} \mathbf{x}_{i} \lambda_{ij} \frac{\mathbf{x}_{j}}{\mathbf{M}_{j}} - \phi_{j} \mathbf{x}_{j} \lambda_{ji} \frac{\mathbf{x}_{i}}{\mathbf{M}_{i}} \right) \right), \end{aligned}$$







Andrew Smith (UQ)





Andrew Smith (UQ)

#### Metapopulation Models

July 10, 2013



Andrew Smith (UQ)

#### Metapopulation Models

July 10, 2013





Andrew Smith (UQ)



Andrew Smith (UQ)



- (A) For all *i* and *j*,  $\lambda_{ij} = 0$  implies  $\lambda_{ji} = 0$ .
- (B) For all *i* and *j*, there is a finite sequence  $(a_k)$  such that  $\lambda_{ia_1}\lambda_{a_1a_2}\ldots\lambda_{a_mj}\neq 0$ .

- (A) For all *i* and *j*,  $\lambda_{ij} = 0$  implies  $\lambda_{ji} = 0$ .
- (B) For all *i* and *j*, there is a finite sequence  $(a_k)$  such that  $\lambda_{ia_1}\lambda_{a_1a_2}\ldots\lambda_{a_mj}\neq 0$ .

### Theorem

Assume (A) and (B) hold. If there exists a  $y \in \mathbb{R}^{J}_{+} \setminus \{\mathbf{0}\}$  such that

$$(b_i(0) - d_i - \phi_i) y_i + \phi_i \sum_{j \neq i}^J \lambda_{ij} y_j \le \mathbf{0}, \quad \text{for all } i, \tag{1}$$

with an inequality for at least one *i*, the fixed point **0** is asymptotically stable. If there is no  $y \in \mathbb{R}^{J}_{+} \setminus \{\mathbf{0}\}$  satisfying (1), then **0** is unstable.

- (A) For all *i* and *j*,  $\lambda_{ij} = 0$  implies  $\lambda_{ji} = 0$ .
- (B) For all *i* and *j*, there is a finite sequence  $(a_k)$  such that  $\lambda_{ia_1}\lambda_{a_1a_2}\ldots\lambda_{a_mj}\neq 0$ .

### Theorem

Assume (A) and (B) hold. If there exists a  $y \in \mathbb{R}^{J}_{+} \setminus \{\mathbf{0}\}$  such that

$$(b_i(0) - d_i - \phi_i) y_i + \phi_i \sum_{j \neq i}^J \lambda_{ij} y_j \le \mathbf{0}, \quad \text{for all } i, \tag{1}$$

with an inequality for at least one *i*, the fixed point **0** is asymptotically stable. If there is no  $y \in \mathbb{R}^{J}_{+} \setminus \{\mathbf{0}\}$  satisfying (1), then **0** is unstable.

If the metapopulation is small enough, it will go extinct.

- (A) For all *i* and *j*,  $\lambda_{ij} = 0$  implies  $\lambda_{ji} = 0$ .
- (B) For all *i* and *j*, there is a finite sequence  $(a_k)$  such that  $\lambda_{ia_1}\lambda_{a_1a_2}\ldots\lambda_{a_mj}\neq 0$ .

### Theorem

Assume (A) and (B) hold. If there exists a  $y \in \mathbb{R}^{J}_{+} \setminus \{\mathbf{0}\}$  such that

$$(b_i(0) - d_i - \phi_i) y_i + \phi_i \sum_{j \neq i}^J \lambda_{ij} y_j \le \mathbf{0}, \quad \text{for all } i, \tag{1}$$

with an inequality for at least one *i*, the fixed point **0** is asymptotically stable. If there is no  $y \in \mathbb{R}^{J}_{+} \setminus \{\mathbf{0}\}$  satisfying (1), then **0** is unstable.

If the metapopulation is small enough, it will go extinct. But what happens if it is unstable?

Andrew Smith (UQ)

### Persistence

### Theorem

Assume (A) and (B) hold. If there is no  $y \in \mathbb{R}^J_+ \setminus \{\mathbf{0}\}$  satisfying

$$(b_i - d_i - \phi_i) y_i + \phi_i \sum_{j \neq i}^J \lambda_{ij} y_j \leq \mathbf{0}, \quad \text{for all } i,$$

then there exists at least one non-zero fixed point  $x^*$  and, for all  $x_0$  such that  $0 < x_0 \le x^*$ ,  $x(t, x_0) \to x^*$ .

### Persistence

### Theorem

Assume (A) and (B) hold. If there is no  $y \in \mathbb{R}^J_+ \setminus \{\mathbf{0}\}$  satisfying

$$(b_i - d_i - \phi_i) y_i + \phi_i \sum_{j \neq i}^J \lambda_{ij} y_j \leq \mathbf{0}, \quad \text{for all } i,$$

then there exists at least one non-zero fixed point  $x^*$  and, for all  $x_0$  such that  $0 < x_0 \le x^*$ ,  $x(t, x_0) \to x^*$ .

As long as the population is not extinct to begin with, it will persist.

### Persistence

### Theorem

Assume (A) and (B) hold. If there is no  $y \in \mathbb{R}^J_+ \setminus \{\mathbf{0}\}$  satisfying

$$(b_i - d_i - \phi_i) y_i + \phi_i \sum_{j \neq i}^J \lambda_{ij} y_j \leq \mathbf{0}, \quad \text{for all } i,$$

then there exists at least one non-zero fixed point  $x^*$  and, for all  $x_0$  such that  $0 < x_0 \le x^*$ ,  $x(t, x_0) \to x^*$ .

As long as the population is not extinct to begin with, it will persist. This theorem implies that the metapopulation will eventually be equal to or larger than  $x^*$ .

# A Sufficient Condition

### • We have determined a *sufficient* condition for survival.

• However, if **0** is stable, will the population necessarily go extinct?

### • We introduce the following assumption

(C) The parameters  $\phi_i$ ,  $\lambda_{ij}$  and  $M_i$  satisfy  $\phi_i \lambda_{ij} M_i = \phi_j \lambda_{ji} M_j$  for all i, j.

• The maximum migration rate to any other empty patch is the same.

# A Sufficient Condition

- We have determined a *sufficient* condition for survival.
- However, if 0 is stable, will the population necessarily go extinct?
- We introduce the following assumption
  - (C) The parameters  $\phi_i$ ,  $\lambda_{ij}$  and  $M_i$  satisfy  $\phi_i \lambda_{ij} M_i = \phi_i \lambda_{ji} M_j$  for all i, j.
- The maximum migration rate to any other empty patch is the same.
# A Sufficient Condition

- We have determined a sufficient condition for survival.
- However, if 0 is stable, will the population necessarily go extinct?
- We introduce the following assumption

(C) The parameters  $\phi_i$ ,  $\lambda_{ij}$  and  $M_i$  satisfy  $\phi_i \lambda_{ij} M_i = \phi_j \lambda_{ji} M_j$  for all i, j.

• The maximum migration rate to any other empty patch is the same.

# A Sufficient Condition

- We have determined a sufficient condition for survival.
- However, if 0 is stable, will the population necessarily go extinct?
- We introduce the following assumption

(C) The parameters  $\phi_i$ ,  $\lambda_{ij}$  and  $M_i$  satisfy  $\phi_i \lambda_{ij} M_i = \phi_j \lambda_{ji} M_j$  for all i, j.

• The maximum migration rate to any other empty patch is the same.

### Extinction

Theorem

Assume (A)–(C) hold. If **0** is stable, then  $x(t, x_0) \rightarrow \mathbf{0}$  for all  $x_0$ .

The metapopulation will go extinct, regardless of its initial size.

### Extinction

#### Theorem

Assume (A)–(C) hold. If **0** is stable, then  $x(t, x_0) \rightarrow \mathbf{0}$  for all  $x_0$ .

The metapopulation will go extinct, regardless of its initial size.

(C) The parameters  $\phi_i$ ,  $\lambda_{ij}$  and  $M_i$  satisfy  $\phi_i \lambda_{ij} M_i = \phi_j \lambda_{ji} M_j$  for all i, j.

### Persistence

#### Theorem

Assume (A)–(C) hold. If **0** is unstable, then there is a unique non-zero fixed point  $x^*$  and  $x(t, x_0) \rightarrow x^*$  for all  $x_0 \neq \mathbf{0}$ .

The metapopulation will persist at the level  $x^*$  provided it is not initially extinct.

(C) The parameters  $\phi_i$ ,  $\lambda_{ij}$  and  $M_i$  satisfy  $\phi_i \lambda_{ij} M_i = \phi_j \lambda_{ji} M_j$  for all i, j.

## **Other Behaviour**

- Under assumption (C), the picture is complete.
- But is the picture the same when (C) doesn't hold?
- Is the persistence of the population purely dependent on the whether the extinction condition is satisfied?
- The Allee effect is when the initial population size determines whether the population will go extinct or persist.
- If the population is large enough, it will persist. Otherwise, it will go extinct.

## **Other Behaviour**

- Under assumption (C), the picture is complete.
- But is the picture the same when (C) doesn't hold?
- Is the persistence of the population purely dependent on the whether the extinction condition is satisfied?
- The Allee effect is when the initial population size determines whether the population will go extinct or persist.
- If the population is large enough, it will persist. Otherwise, it will go extinct.

## Demonstrating the Allee Effect



## Demonstrating the Allee Effect

## Influence due to the Environment

- Previously, we assumed that the birth, death and migration rates were constant with respect to time.
- However, is this a reasonable assumption? Is it reasonable over a long period of time?
- What happens if the environment changes?
  - Breeding seasons,
  - Migration paths cut,
  - Catastrophes,
  - And various others.
- Some influences are deterministic and can be accounted for with a similar functional law of large numbers.
- But others are stochastic.

## Influence due to the Environment

- Previously, we assumed that the birth, death and migration rates were constant with respect to time.
- However, is this a reasonable assumption? Is it reasonable over a long period of time?
- What happens if the environment changes?
  - Breeding seasons,
  - Migration paths cut,
  - Catastrophes,
  - And various others.
- Some influences are deterministic and can be accounted for with a similar functional law of large numbers.
- But others are stochastic.

## Influence due to the Environment

- Previously, we assumed that the birth, death and migration rates were constant with respect to time.
- However, is this a reasonable assumption? Is it reasonable over a long period of time?
- What happens if the environment changes?
  - Breeding seasons,
  - Migration paths cut,
  - Catastrophes,
  - And various others.
- Some influences are deterministic and can be accounted for with a similar functional law of large numbers.
- But others are stochastic.

- To account for this, we let our parameters depend on a variable that models the environment.
- Define *C*(*t*) to be the configuration we are in at time *t* and assume there are only *K* configurations.
- As before,  $n_i(t)$  is the number of individuals on patch *i*. The process (C(t), n(t)) has state space  $\{1, \ldots, K\} \times S_N$  and the following transition rates:

$$q((C, n), (C, n) + (0, e_i)) = b_i^{(C)} \frac{n_i}{N_i} (N_i - n_i),$$
  

$$q((C, n), (C, n) + (0, -e_i)) = \phi_i^{(C)} n_i \lambda_{i0}^{(C)} + d_i^{(C)} n_i,$$
  

$$f((C, n), (C, n) + (0, -e_i + e_j)) = \phi_i^{(C)} n_i \lambda_{ij}^{(C)} \frac{N_j - n_j}{N_j} \quad \forall j \neq i,$$

- To account for this, we let our parameters depend on a variable that models the environment.
- Define *C*(*t*) to be the configuration we are in at time *t* and assume there are only *K* configurations.
- As before,  $n_i(t)$  is the number of individuals on patch *i*. The process (C(t), n(t)) has state space  $\{1, \ldots, K\} \times S_N$  and the following transition rates:

$$q((C, n), (C, n) + (0, e_i)) = b_i^{(C)} \frac{n_i}{N_i} (N_i - n_i),$$
  

$$q((C, n), (C, n) + (0, -e_i)) = \phi_i^{(C)} n_i \lambda_{i0}^{(C)} + d_i^{(C)} n_i,$$
  

$$((C, n), (C, n) + (0, -e_i + e_j)) = \phi_i^{(C)} n_i \lambda_{ij}^{(C)} \frac{N_j - n_j}{N_j} \quad \forall j \neq i,$$

- To account for this, we let our parameters depend on a variable that models the environment.
- Define *C*(*t*) to be the configuration we are in at time *t* and assume there are only *K* configurations.
- As before,  $n_i(t)$  is the number of individuals on patch *i*. The process (C(t), n(t)) has state space  $\{1, \ldots, K\} \times S_N$  and the following transition rates:

$$q((C, n), (C, n) + (0, e_i)) = b_i^{(C)} \frac{n_i}{N_i} (N_i - n_i),$$
  

$$q((C, n), (C, n) + (0, -e_i)) = \phi_i^{(C)} n_i \lambda_{i0}^{(C)} + d_i^{(C)} n_i,$$
  

$$q((C, n), (C, n) + (0, -e_i + e_j)) = \phi_i^{(C)} n_i \lambda_{ij}^{(C)} \frac{N_j - n_j}{N_j} \quad \forall j \neq i,$$

- To account for this, we let our parameters depend on a variable that models the environment.
- Define *C*(*t*) to be the configuration we are in at time *t* and assume there are only *K* configurations.
- As before,  $n_i(t)$  is the number of individuals on patch *i*. The process (C(t), n(t)) has state space  $\{1, \ldots, K\} \times S_N$  and the following transition rates:

$$q((C, n), (C, n) + (0, e_i)) = b_i^{(C)} \frac{n_i}{N_i} (N_i - n_i),$$
  

$$q((C, n), (C, n) + (0, -e_i)) = \phi_i^{(C)} n_i \lambda_{i0}^{(C)} + d_i^{(C)} n_i,$$
  

$$q((C, n), (C, n) + (0, -e_i + e_j)) = \phi_i^{(C)} n_i \lambda_{ij}^{(C)} \frac{N_j - n_j}{N_j} \quad \forall j \neq i,$$
  

$$q((C, n), (C, n) + (l_i, \mathbf{0})) = g_i (C, n/N), \text{ for } i = 1, \dots, k.$$

- To account for this, we let our parameters depend on a variable that models the environment.
- Define *C*(*t*) to be the configuration we are in at time *t* and assume there are only *K* configurations.
- As before,  $n_i(t)$  is the number of individuals on patch *i*. The process (C(t), n(t)) has state space  $\{1, \ldots, K\} \times S_N$  and the following transition rates:

$$q((C, n), (C, n) + (0, e_i)) = b_i^{(C)} \frac{n_i}{N_i} (N_i - n_i),$$
  

$$q((C, n), (C, n) + (0, -e_i)) = \phi_i^{(C)} n_i \lambda_{i0}^{(C)} + d_i^{(C)} n_i,$$
  

$$q((C, n), (C, n) + (0, -e_i + e_j)) = \phi_i^{(C)} n_i \lambda_{ij}^{(C)} \frac{N_j - n_j}{N_j} \quad \forall j \neq i,$$
  

$$q((C, n), (C, n) + (l_i, \mathbf{0})) = g_i (C, n/N), \text{ for } i = 1, \dots, k.$$

#### Theorem

Assume g is smooth. Then if,  $\lim_{N\to\infty} Y_N(0) \to y_0$ , then a.s.  $Y_N(t) \to Y(t)$ , in Skorokhod topology, where Y(t) is given by

$$Y(t) = y_0 + \sum_{i=1}^{K} \left( I_i, \mathbf{0}^T \right) \prod_i \left( \int_0^t g_i \left( Y(s) \right) ds \right) + \int_0^t V(Y(s)) ds, \qquad (2)$$

$$\begin{split} V_{1}(c,x) &= 0, \\ V_{1+i}(c,x) &= F_{i}^{(c)}(x) = \left( b_{i}^{(c)} - d_{i}^{(c)} - \phi_{i}^{(c)} \right) x_{i} - \frac{b_{i}^{(c)}}{M_{i}} x_{i}^{2} \\ &+ \sum_{j \neq i} \left( \phi_{j}^{(c)} x_{j} \lambda_{ji} + \left( \phi_{i}^{(c)} x_{i} \lambda_{ij}^{(c)} \frac{x_{j}}{M_{j}} - \phi_{j}^{(c)} x_{j} \lambda_{ji}^{(c)} \frac{x_{i}}{M_{i}} \right) \right). \end{split}$$

#### Theorem

Assume g is smooth. Then if,  $\lim_{N\to\infty} Y_N(0) \to y_0$ , then a.s.  $Y_N(t) \to Y(t)$ , in Skorokhod topology, where Y(t) is given by

$$Y(t) = y_0 + \sum_{i=1}^{K} \left( I_i, \mathbf{0}^T \right) \prod_i \left( \int_0^t g_i \left( Y(s) \right) ds \right) + \int_0^t V(Y(s)) ds, \qquad (2)$$

$$\begin{split} V_{1}(c,x) &= 0, \\ V_{1+i}(c,x) &= F_{i}^{(c)}(x) = \left( b_{i}^{(c)} - d_{i}^{(c)} - \phi_{i}^{(c)} \right) x_{i} - \frac{b_{i}^{(c)}}{M_{i}} x_{i}^{2} \\ &+ \sum_{j \neq i} \left( \phi_{j}^{(c)} x_{j} \lambda_{ji} + \left( \phi_{i}^{(c)} x_{i} \lambda_{ij}^{(c)} \frac{x_{j}}{M_{j}} - \phi_{j}^{(c)} x_{j} \lambda_{ji}^{(c)} \frac{x_{i}}{M_{i}} \right) \right). \end{split}$$

#### Theorem

Assume g is smooth. Then if,  $\lim_{N\to\infty} Y_N(0) \to y_0$ , then a.s.  $Y_N(t) \to Y(t)$ , in Skorokhod topology, where Y(t) is given by

$$Y(t) = \mathbf{y}_0 + \sum_{i=1}^{K} (l_i, \mathbf{0}^T) \Pi_i \left( \int_0^t g_i(Y(s)) \, ds \right) + \int_0^t V(Y(s)) \, ds, \qquad (2)$$

$$\begin{split} V_{1}(c,x) &= 0, \\ V_{1+i}(c,x) &= F_{i}^{(c)}(x) = \left( b_{i}^{(c)} - d_{i}^{(c)} - \phi_{i}^{(c)} \right) x_{i} - \frac{b_{i}^{(c)}}{M_{i}} x_{i}^{2} \\ &+ \sum_{j \neq i} \left( \phi_{j}^{(c)} x_{j} \lambda_{ji} + \left( \phi_{i}^{(c)} x_{i} \lambda_{ji}^{(c)} \frac{x_{j}}{M_{j}} - \phi_{j}^{(c)} x_{j} \lambda_{ji}^{(c)} \frac{x_{i}}{M_{i}} \right) \right). \end{split}$$

#### Theorem

Assume g is smooth. Then if,  $\lim_{N\to\infty} Y_N(0) \to y_0$ , then a.s.  $Y_N(t) \to Y(t)$ , in Skorokhod topology, where Y(t) is given by

$$Y(t) = y_0 + \sum_{i=1}^{K} \left( I_i, \mathbf{0}^T \right) \prod_i \left( \int_0^t g_i \left( Y(s) \right) ds \right) + \int_0^t V(Y(s)) ds, \qquad (2)$$

$$\begin{split} V_{1}(c,x) &= 0, \\ V_{1+i}(c,x) &= F_{i}^{(c)}(x) = \left( b_{i}^{(c)} - d_{i}^{(c)} - \phi_{i}^{(c)} \right) x_{i} - \frac{b_{i}^{(c)}}{M_{i}} x_{i}^{2} \\ &+ \sum_{j \neq i} \left( \phi_{j}^{(c)} x_{j} \lambda_{ji} + \left( \phi_{i}^{(c)} x_{i} \lambda_{ij}^{(c)} \frac{x_{j}}{M_{j}} - \phi_{j}^{(c)} x_{j} \lambda_{ji}^{(c)} \frac{x_{i}}{M_{i}} \right) \right). \end{split}$$

- As the environment changes, what happens to the metapopulation as *t* gets large?
- The metapopulation size is deterministic until a configuration transition.
- Let  $\tau_i$  be the time between the (i 1)th and *i*th jump between configurations (noting that  $\tau_0 = 0$ ), N(t) be the number of jumps at time *t* and  $J_c = \nabla F^{(c)}(0)$ . Then

$$\begin{aligned} x(t) = \exp\left(J_{C(t)}\left(t - \sum_{i=1}^{N(t)} \tau_i\right)\right) x\left(\tau_{N(t)}\right) \\ - \int_{\tau_{N(t)}}^{t} \exp\left(J_{C(t)}\left(t - s\right)\right) \tilde{F}^{(C(s))}(x(s)) ds \end{aligned}$$

• It is known that  $\exp \left(J_{C(t)}\left(t-s\right)\right)$  is positive

- As the environment changes, what happens to the metapopulation as *t* gets large?
- The metapopulation size is deterministic until a configuration transition.
- Let  $\tau_i$  be the time between the (i 1)th and *i*th jump between configurations (noting that  $\tau_0 = 0$ ), N(t) be the number of jumps at time *t* and  $J_c = \nabla F^{(c)}(0)$ . Then

$$\begin{aligned} x(t) = \exp\left(J_{C(t)}\left(t - \sum_{i=1}^{N(t)} \tau_i\right)\right) x\left(\tau_{N(t)}\right) \\ - \int_{\tau_{N(t)}}^{t} \exp\left(J_{C(t)}\left(t - s\right)\right) \tilde{F}^{(C(s))}(x(s)) ds \end{aligned}$$

• It is known that  $\exp (J_{C(t)}(t-s))$  is positive

- As the environment changes, what happens to the metapopulation as *t* gets large?
- The metapopulation size is deterministic until a configuration transition.
- Let  $\tau_i$  be the time between the (i 1)th and *i*th jump between configurations (noting that  $\tau_0 = 0$ ), N(t) be the number of jumps at time *t* and  $J_c = \nabla F^{(c)}(0)$ . Then

$$\begin{aligned} \mathbf{x}(t) = \exp\left(J_{C(t)}\left(t - \sum_{i=1}^{N(t)} \tau_i\right)\right) \mathbf{x}\left(\tau_{N(t)}\right) \\ - \int_{\tau_{N(t)}}^{t} \exp\left(J_{C(t)}\left(t - s\right)\right) \tilde{F}^{(C(s))}(\mathbf{x}(s)) ds. \end{aligned}$$

• It is known that  $\exp (J_{C(t)}(t-s))$  is positive

- As the environment changes, what happens to the metapopulation as *t* gets large?
- The metapopulation size is deterministic until a configuration transition.
- Let  $\tau_i$  be the time between the (i 1)th and *i*th jump between configurations (noting that  $\tau_0 = 0$ ), N(t) be the number of jumps at time *t* and  $J_c = \nabla F^{(c)}(0)$ . Then

$$\begin{aligned} \mathbf{x}(t) = \exp\left(J_{C(t)}\left(t - \sum_{i=1}^{N(t)} \tau_i\right)\right) \mathbf{x}\left(\tau_{N(t)}\right) \\ - \int_{\tau_{N(t)}}^{t} \exp\left(J_{C(t)}\left(t - s\right)\right) \tilde{F}^{(C(s))}(\mathbf{x}(s)) ds \end{aligned}$$

• It is known that  $\exp \left( J_{\mathcal{C}(t)} \left( t - s \right) \right)$  is positive

- As the environment changes, what happens to the metapopulation as *t* gets large?
- The metapopulation size is deterministic until a configuration transition.
- Let  $\tau_i$  be the time between the (i 1)th and *i*th jump between configurations (noting that  $\tau_0 = 0$ ), N(t) be the number of jumps at time *t* and  $J_c = \nabla F^{(c)}(0)$ . Then

$$\begin{aligned} \mathbf{x}(t) = \exp\left(J_{C(t)}\left(t - \sum_{i=1}^{N(t)} \tau_i\right)\right) \mathbf{x}\left(\tau_{N(t)}\right) \\ - \int_{\tau_{N(t)}}^{t} \exp\left(J_{C(t)}\left(t - s\right)\right) \tilde{F}^{(C(s))}(\mathbf{x}(s)) ds \end{aligned}$$

• It is known that  $\exp (J_{C(t)}(t-s))$  is positive and under Assumption (C),  $\tilde{F}^{(c)}(x) \ge 0$ .

- As the environment changes, what happens to the metapopulation as *t* gets large?
- The metapopulation size is deterministic until a configuration transition.
- Let  $\tau_i$  be the time between the (i 1)th and *i*th jump between configurations (noting that  $\tau_0 = 0$ ), N(t) be the number of jumps at time *t* and  $J_c = \nabla F^{(c)}(0)$ . Then

$$\begin{aligned} \mathbf{x}(t) &= \exp\left(J_{C(t)}\left(t - \sum_{i=1}^{N(t)} \tau_i\right)\right) \mathbf{x}\left(\tau_{N(t)}\right) \\ &- \int_{\tau_{N(t)}}^{t} \exp\left(J_{C(t)}\left(t - s\right)\right) \tilde{F}^{(C(s))}(\mathbf{x}(s)) ds. \end{aligned}$$

• It is known that  $\exp (J_{C(t)}(t-s))$  is positive and under Assumption (C),  $\tilde{F}^{(c)}(x) \ge 0$ .

- If the linear process converges to **0**, then  $x(t) \rightarrow \mathbf{0}$ .
- Let us consider linear process, *z*(*t*):

$$z(t) = f(t) \left(\prod_{i=1}^{N(t)} \exp\left(J_{c_{i-1}}\tau_i\right)\right) x_0,$$

where

$$f(t) = \exp\left(J_{\mathcal{C}_{\mathcal{N}(t)}}\left(t - \sum_{i=1}^{\mathcal{N}(t)} \tau_i\right)\right).$$

• Define  $r_i$  as the largest real part of  $\sigma(J_i)$ . If  $\phi_i^{(c)}\lambda_{ij}^{(c)} = \rho_c \,\forall i, j$ , then

$$\mathbb{P}\left(|z(t)| < \varepsilon\right) \geq \mathbb{P}\left(N(t)\sum_{i=1}^{K} r_i \frac{N_i(t)}{N(t)} \frac{1}{N_i(t)} \sum_{j=1}^{N_i(t)} \tau_{ij} < \log\left(\frac{\varepsilon}{c|M|}\right)\right).$$

- If the linear process converges to **0**, then  $x(t) \rightarrow \mathbf{0}$ .
- Let us consider linear process, *z*(*t*):

$$z(t) = f(t) \left( \prod_{i=1}^{N(t)} \exp \left( J_{C_{i-1}} \tau_i \right) \right) x_0,$$

where

$$f(t) = \exp\left(J_{\mathcal{C}_{\mathcal{N}(t)}}\left(t - \sum_{i=1}^{\mathcal{N}(t)} \tau_i\right)\right).$$

• Define  $r_i$  as the largest real part of  $\sigma(J_i)$ . If  $\phi_i^{(c)}\lambda_{ij}^{(c)} = \rho_c \,\forall i, j$ , then

$$\mathbb{P}\left(|z(t)| < \varepsilon\right) \geq \mathbb{P}\left(N(t)\sum_{i=1}^{K} r_i \frac{N_i(t)}{N(t)} \frac{1}{N_i(t)} \sum_{j=1}^{N_i(t)} \tau_{ij} < \log\left(\frac{\varepsilon}{c|M|}\right)\right).$$

- If the linear process converges to **0**, then  $x(t) \rightarrow \mathbf{0}$ .
- Let us consider linear process, *z*(*t*):

$$z(t) = f(t) \left( \prod_{i=1}^{N(t)} \exp \left( J_{c_{i-1}} \tau_i \right) \right) x_0,$$

where

$$f(t) = \exp\left(J_{c_{N(t)}}\left(t - \sum_{i=1}^{N(t)} \tau_i\right)\right).$$

• Define  $r_i$  as the largest real part of  $\sigma(J_i)$ . If  $\phi_i^{(c)}\lambda_{ij}^{(c)} = \rho_c \forall i, j$ , then

$$\mathbb{P}\left(|\boldsymbol{z}(t)| < \varepsilon\right) \geq \mathbb{P}\left(N(t)\sum_{i=1}^{K} r_i \frac{N_i(t)}{N(t)} \frac{1}{N_i(t)} \sum_{j=1}^{N_i(t)} \tau_{ij} < \log\left(\frac{\varepsilon}{c |\boldsymbol{M}|}\right)\right).$$

- If the linear process converges to **0**, then  $x(t) \rightarrow \mathbf{0}$ .
- Let us consider linear process, *z*(*t*):

$$z(t) = f(t) \left( \prod_{i=1}^{N(t)} \exp\left(J_{C_{i-1}}\tau_i\right) \right) x_0,$$

where

$$|f(t)| = \left| \exp \left( J_{C_{N(t)}} \left( t - \sum_{i=1}^{N(t)} \tau_i \right) \right) \right| \leq c.$$

• Define  $r_i$  as the largest real part of  $\sigma(J_i)$ . If  $\phi_i^{(c)}\lambda_{ij}^{(c)} = \rho_c \forall i, j$ , then

$$\mathbb{P}\left(|\boldsymbol{z}(t)| < \varepsilon\right) \geq \mathbb{P}\left(N(t)\sum_{i=1}^{K} r_i \frac{N_i(t)}{N(t)} \frac{1}{N_i(t)} \sum_{j=1}^{N_i(t)} \tau_{ij} < \log\left(\frac{\varepsilon}{\boldsymbol{c} |\boldsymbol{M}|}\right)\right).$$

- If the linear process converges to **0**, then  $x(t) \rightarrow \mathbf{0}$ .
- Let us consider linear process, *z*(*t*):

$$z(t) = f(t) \left( \prod_{i=1}^{N(t)} \exp\left(J_{C_{i-1}}\tau_i\right) \right) x_0,$$

where

$$|f(t)| = \left| \exp \left( J_{C_{N(t)}} \left( t - \sum_{i=1}^{N(t)} \tau_i \right) \right) \right| \leq c.$$

• Define  $r_i$  as the largest real part of  $\sigma(J_i)$ . If  $\phi_i^{(c)}\lambda_{ij}^{(c)} = \rho_c \forall i, j$ , then

$$\mathbb{P}\left(|\boldsymbol{z}(t)| < \varepsilon\right) \geq \mathbb{P}\left(N(t)\sum_{i=1}^{K} r_i \frac{N_i(t)}{N(t)} \frac{1}{N_i(t)} \sum_{j=1}^{N_i(t)} \tau_{ij} < \log\left(\frac{\varepsilon}{c |M|}\right)\right),$$

where  $N_i(t)$  is the number of visits for configuration *i* at time *t*.

- If the linear process converges to **0**, then  $x(t) \rightarrow \mathbf{0}$ .
- Let us consider linear process, *z*(*t*):

$$z(t) = f(t) \left( \prod_{i=1}^{N(t)} \exp\left(J_{C_{i-1}}\tau_i\right) \right) x_0,$$

where

$$|f(t)| = \left| \exp \left( J_{C_{N(t)}} \left( t - \sum_{i=1}^{N(t)} \tau_i \right) \right) \right| \leq c.$$

• Define  $r_i$  as the largest real part of  $\sigma(J_i)$ . If  $\phi_i^{(c)}\lambda_{ij}^{(c)} = \rho_c \forall i, j$ , then

$$\mathbb{P}\left(|\boldsymbol{z}(t)| < \varepsilon\right) \geq \mathbb{P}\left(N(t)\sum_{i=1}^{K} r_i \frac{N_i(t)}{N(t)} \frac{1}{N_i(t)} \sum_{j=1}^{N_i(t)} \tau_{ij} < \log\left(\frac{\varepsilon}{c |M|}\right)\right),$$

where  $\tau_{ij}$  is the length of the *j*th visit to the *i*th configuration.

- If the linear process converges to **0**, then  $x(t) \rightarrow \mathbf{0}$ .
- Let us consider linear process, *z*(*t*):

$$z(t) = f(t) \left( \prod_{i=1}^{N(t)} \exp\left(J_{C_{i-1}}\tau_i\right) \right) x_0,$$

where

$$|f(t)| = \left| \exp \left( J_{C_{N(t)}} \left( t - \sum_{i=1}^{N(t)} \tau_i \right) \right) \right| \leq c.$$

• Define  $r_i$  as the largest real part of  $\sigma(J_i)$ . If  $\phi_i^{(c)}\lambda_{ij}^{(c)} = \rho_c \forall i, j$ , then

$$\mathbb{P}\left(|z(t)| < \varepsilon\right) \geq \mathbb{P}\left(N(t)\sum_{i=1}^{K} r_i \frac{N_i(t)}{N(t)} \frac{1}{N_i(t)} \sum_{j=1}^{N_i(t)} \tau_{ij} < \log\left(\frac{\varepsilon}{c |M|}\right)\right).$$

• Define  $\eta_i := \lim_{t \to \infty} N_i(t) / N(t) > 0$  and assume, for a given *i* that each  $\tau_{ij}$  is i.i.d. Then  $\frac{1}{n} \sum_{j=1}^n \tau_{ij} \to \mathbb{E}\tau_{ij} = \left(\sum_{j=1}^k g_j(i)\right)^{-1}$ .

#### Theorem

Assume the metapopulation has K configurations and  $\phi_i^{(c)} \lambda_{ii}^{(c)} = \rho_c \ \forall i, j$ . Then for any  $\varepsilon > 0$ 

$$\sum_{i=1}^{K} r_i \eta_i \left( \sum_{j=1}^{k} g_j(i) \right)^{-1} < 0 \implies \lim_{t \to \infty} \mathbb{P}\left( |x(t)| > \varepsilon \right) \to 0.$$

• Define  $\eta_i := \lim_{t\to\infty} N_i(t)/N(t) > 0$  and assume, for a given *i* that each  $\tau_{ij}$  is i.i.d. Then  $\frac{1}{n} \sum_{j=1}^n \tau_{ij} \to \mathbb{E}\tau_{ij} = \left(\sum_{j=1}^k g_j(i)\right)^{-1}$ .

#### Theorem

Assume the metapopulation has K configurations and  $\phi_i^{(c)}\lambda_{ij}^{(c)} = \rho_c \ \forall i, j.$  Then for any  $\varepsilon > 0$ 

$$\sum_{i=1}^{K} r_i \eta_i \left( \sum_{j=1}^{k} g_j(i) \right)^{-1} < 0 \implies \lim_{t \to \infty} \mathbb{P}\left( |x(t)| > \varepsilon \right) \to 0.$$


 $r_1 = 13.07, r_2 = -29.35, \mathbb{E}\tau_{1j} = 1/5, \mathbb{E}\tau_{2j} = 1/9$ 

Andrew Smith (UQ)



 $r_1 = 27.01, r_2 = -14.11, \mathbb{E}\tau_{1j} = 1/4, \mathbb{E}\tau_{2j} = 1/2$ 

Andrew Smith (UQ)



 $r_1 = 16.83, r_2 = -25.70, \mathbb{E}\tau_{1j} = 1/11, \mathbb{E}\tau_{2j} = 1/8$ 

Andrew Smith (UQ)



 $r_1 = 10.63, r_2 = -5.60, \mathbb{E}\tau_{1j} = 1/5, \mathbb{E}\tau_{2j} = 1/10$ 

Andrew Smith (UQ)



 $r_1 = 23.10, r_2 = -13.74, \mathbb{E}\tau_{1j} = 1, \mathbb{E}\tau_{2j} = 1/8$ 

Andrew Smith (UQ)



 $r_1 = 27.06, r_2 = -22.60, \mathbb{E}\tau_{1j} = 1, \mathbb{E}\tau_{2j} = 1/5$ 

Andrew Smith (UQ)

## Summary

I have:

- Derived a metapopulation model that is structured spatially and accounts for with-in patch dynamics.
- Approximated the stochastic metapopulation by a dynamical system, and determined conditions for extinction and persistence.
- Introduced stochastic environmental influence.
- Approximated the stochastic environmental influence by a piecewise deterministic Markov process (PDMP).
- Determined conditions for extinction under a strict symmetry condition.

In the future, I plan to:

- Determine explicitly when the Allee effect occurs for an arbitrarily sized metapopulation.
- Weaken the symmetry assumptions for the original process and the PDMP.
- Determine when the PDMP will persist.

- The ARC Centre of Excellence for MASCOS
- My supervisors & fellow postgraduate students

# Questions?



AUSTRALIAN RESEARCH COUNCIL Centre of Excellence for Mathematics and Statistics of Complex Systems

