

Finite Buffer Queueing/Fluid Networks with Overflows

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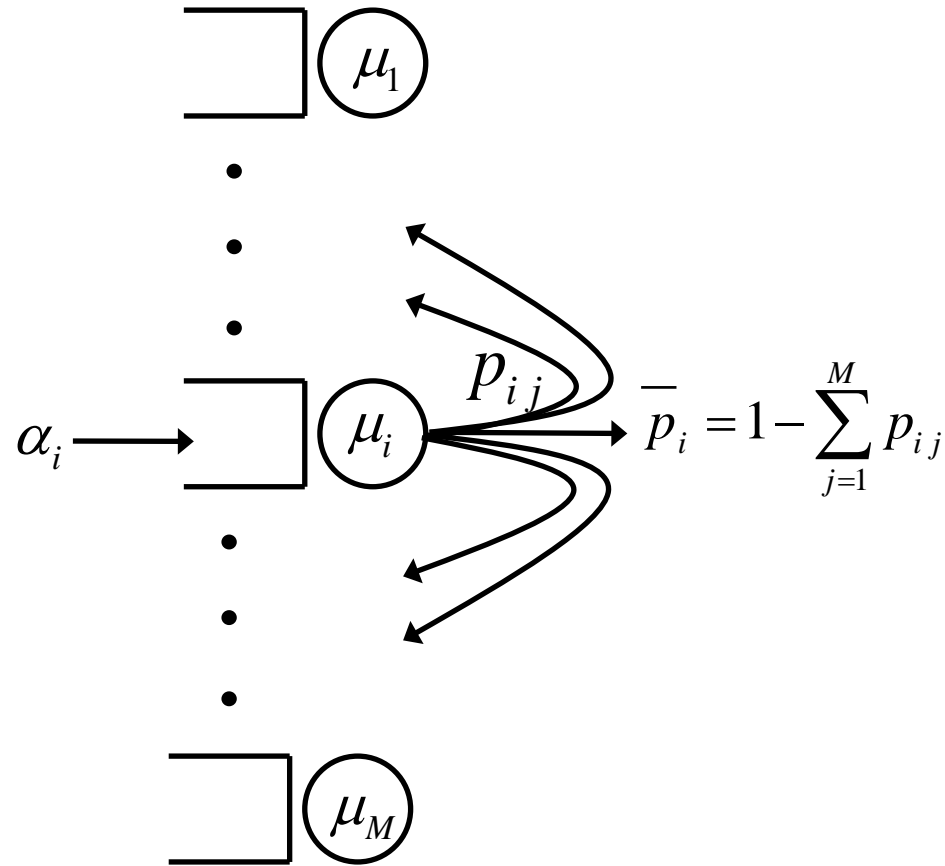
Swinburne Applied Mathematics Seminar,
April Fools' Day, 2011.

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Background Jackson Networks and LCP

Open Jackson Networks

Jackson 1957, Goodman & Massey 1984, Chen & Mandelbaum 1991



Problem Data:

$$\mu_M, \alpha_M, P_{M \times M}$$

Assume: open, no “dead” nodes

Traffic Equations (Stable Case):

$$\lambda_i = \alpha_i + \sum_{j=1}^M \lambda_j p_{ji}$$

$$\lambda = \alpha + P' \lambda$$

$$\lambda = (I - P')^{-1} \alpha$$

Traffic Equations (General Case):

$$\lambda_i = \alpha_i + \sum_{j=1}^M (\lambda_j \wedge \mu_j) p_{ji}$$

$$\lambda = \alpha + P'(\lambda \wedge \mu)$$

$$LCP(\alpha - (I - P')\mu, (I - P'))$$

The Linear Complementarity Problem (LCP)

$$q \in \mathbb{R}^n, M \in \mathbb{R}^{n \times n}$$

LCP(q, M): Find $z, w \in \mathbb{R}^n$:

$$w - Mz = q,$$

$$w \geq 0, z \geq 0,$$

$$w'z = 0.$$

The last (complementarity) condition reads:

$$w_i > 0 \Rightarrow z_i = 0 \quad \text{and} \quad z_i > 0 \Rightarrow w_i = 0.$$

Min-Linear Equations (Using LCP)

Find λ :

$$\lambda = \gamma + B(\lambda \wedge \mu)$$

$$\delta = \lambda \wedge \mu$$

$$\lambda = \gamma + B\delta$$

$$0 \leq \delta \leq \lambda$$

$$0 \leq \delta \leq \mu$$

$$(\lambda - \delta)'(\mu - \delta) = 0$$

$$w - (I - B)z = \gamma - (I - B)\mu$$

$$z \geq 0, w \geq 0$$

$$w'z = 0$$

$$w = \lambda - \delta, z = \mu - \delta$$

$$LCP(\gamma - (I - B)\mu, I - B)$$

Classic Product Form Results

Jackson 1957, Goodman & Massey 1984

Again the Traffic Equations :

$$\lambda_i = \alpha_i + \sum_{j=1}^M (\lambda_j \wedge \mu_j) p_{ji}$$

$$\lambda = \alpha + P'(\lambda \wedge \mu)$$

$$LCP(\alpha - (I - P')\mu , (I - P'))$$

Assume arrivals are Poisson processes and i.i.d. exponential service durations

Jackson 57': When $\lambda_i < \mu_i$ $i = 1, \dots, M$:

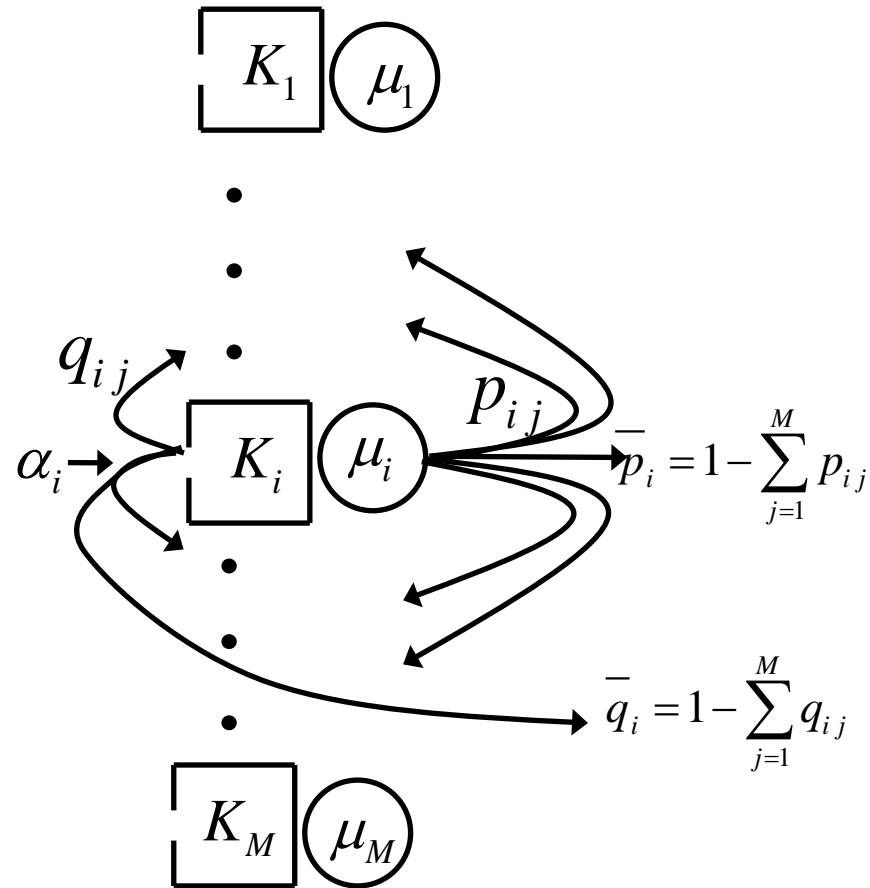
$$\lim_{t \rightarrow \infty} P(X_1(t) = x_1, \dots, X_M(t) = x_M) = \prod_{i=1}^M \left(1 - \frac{\lambda_i}{\mu_i}\right) \left(\frac{\lambda_i}{\mu_i}\right)^{x_i}$$

G&M 84': On the set of non-overloaded nodes product form holds ($\lambda_i < \mu_i$) and the other nodes diverge to infinity a.s.

Our Contribution:
Finite Buffers with Overflows

Modification: Finite Buffers and Overflows

Practically important but not as tractable



Problem Data:

$$\mu_M, \alpha_M, P_{M \times M}, K_M, Q_{M \times M}$$

Assume: open, no “dead” nodes, no “jam” (open overflows)

Exact Traffic Equations:

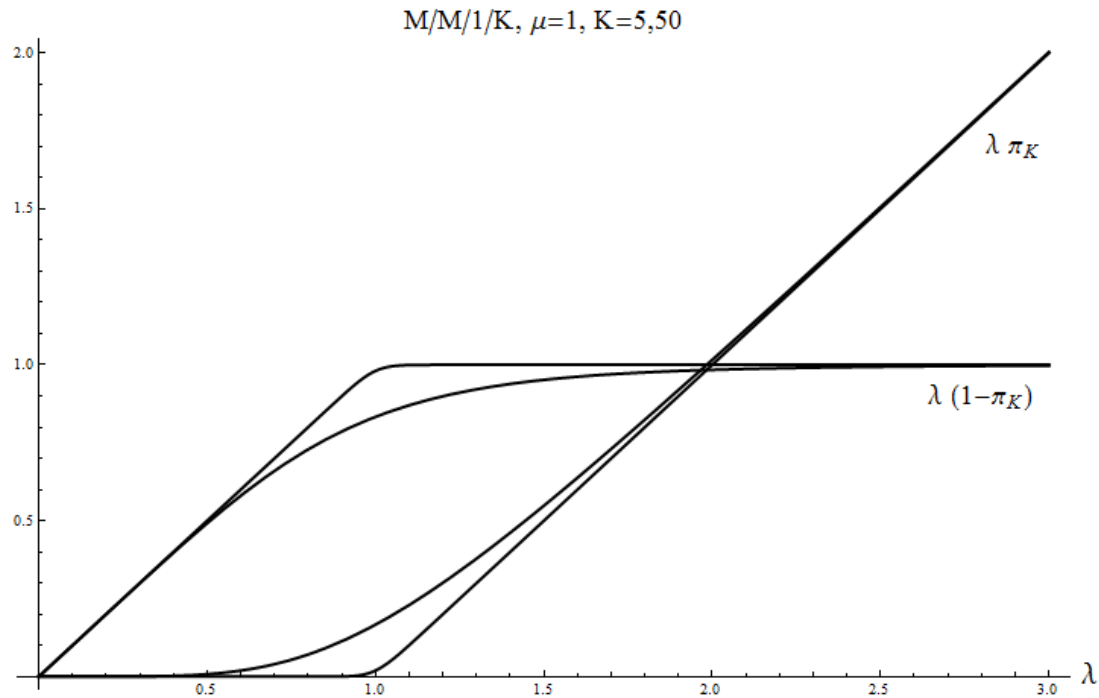
Generally No

Explicit Solutions:

Generally No

Nico van Dijk, 1988. Yes if $P=Q$.

When K is Big, Things are “Simpler”



$$\text{out rate} \approx \lambda \wedge \mu$$

For K big:

$$\text{overflow rate} \approx \lambda - \lambda \wedge \mu = (\lambda - \mu)^+$$

So scale the system with $N = 1, 2, \dots$:

$$\alpha^N = N \alpha$$

$$\mu^N = N \mu$$

$$K^N = N K$$

Limiting Traffic Equations

limiting out rate = $\lambda \wedge \mu$

limiting overflow rate = $(\lambda - \mu)^+$

$$\lambda_i = \alpha_i + \sum_{j=1}^M (\lambda_j \wedge \mu_j) p_{ji} + \sum_{j=1}^M (\lambda_j - \mu_j)^+ q_{ji}$$

or

$$\lambda = \alpha + P'(\lambda \wedge \mu) + Q'(\lambda - \mu)^+$$

or

$$\lambda = \alpha + P'(\lambda \wedge \mu) + Q'(\lambda - \lambda \wedge \mu)$$

$$\lambda = (I - Q')^{-1} \alpha + (I - Q')^{-1} (P' - Q') (\lambda \wedge \mu)$$

$$LCP \left((I - Q')^{-1} (\alpha - (I - P') \mu), (I - Q')^{-1} (I - P') \right)$$

Digression:

The Linear Complementarity Problem (LCP)

The Linear Complementarity Problem (LCP)

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It's all about Choosing a Subset...

For $\alpha \subseteq \{1, \dots, n\}$ denote by $B(\alpha)$ a matrix with columns α taken from I (identity matrix) and columns $\{1, \dots, n\} \setminus \alpha$ taken from $-M$.

LCP is about finding α and $x \geq 0$ such that

$$B(\alpha) x = q$$

In this case:

$$w_i = \begin{cases} x_i & i \in \alpha \\ 0 & i \notin \alpha \end{cases}, \quad z_i = \begin{cases} 0 & i \in \alpha \\ x_i & i \notin \alpha \end{cases}.$$

Illustration: n=2

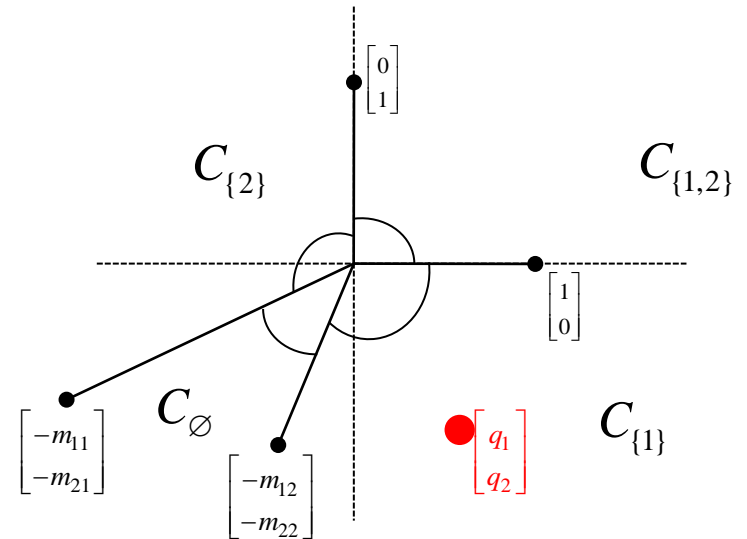
$$\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} w_1 \\ w_2 \end{bmatrix} - \begin{bmatrix} m_{11} & m_{12} \\ m_{21} & m_{22} \end{bmatrix} \begin{bmatrix} z_1 \\ z_2 \end{bmatrix} = \begin{bmatrix} q_1 \\ q_2 \end{bmatrix}$$

$$\alpha = \{1, 2\}: \begin{bmatrix} 1 \\ 0 \end{bmatrix} w_1 + \begin{bmatrix} 0 \\ 1 \end{bmatrix} w_2 = \begin{bmatrix} q_1 \\ q_2 \end{bmatrix}$$

$$\alpha = \{1\}: \begin{bmatrix} 1 \\ 0 \end{bmatrix} w_1 + \begin{bmatrix} -m_{12} \\ -m_{22} \end{bmatrix} z_2 = \begin{bmatrix} q_1 \\ q_2 \end{bmatrix}$$

$$\alpha = \{2\}: \begin{bmatrix} -m_{11} \\ -m_{21} \end{bmatrix} z_1 + \begin{bmatrix} 0 \\ 1 \end{bmatrix} w_2 = \begin{bmatrix} q_1 \\ q_2 \end{bmatrix}$$

$$\alpha = \emptyset: \begin{bmatrix} -m_{11} \\ -m_{21} \end{bmatrix} z_1 + \begin{bmatrix} -m_{12} \\ -m_{22} \end{bmatrix} z_2 = \begin{bmatrix} q_1 \\ q_2 \end{bmatrix}$$



Complementary cones:

$$C_\alpha = \{y : y = B(\alpha)u, u \geq 0\}$$

Immediate naïve algorithm with complexity

$$2^n n^3 \quad \text{or} \quad 2^n + n^3$$

Existence and Uniqueness

Definition: A matrix, $M \in \mathbb{R}^{n \times n}$ is a P-matrix if the determinants of all $(2^n - 1)$ principal submatrices are positive.

Theorem (1958): $LCP(q, M)$ has a unique solution for all $q \in \mathbb{R}^n$ if and only if M is a P-matrix.

e.g. for $n = 2$: $m_{11} > 0$, $m_{22} > 0$, $m_{11}m_{22} - m_{12}m_{21} > 0$

P-matrix means that the complementary cones "partition" \mathbb{R}^n

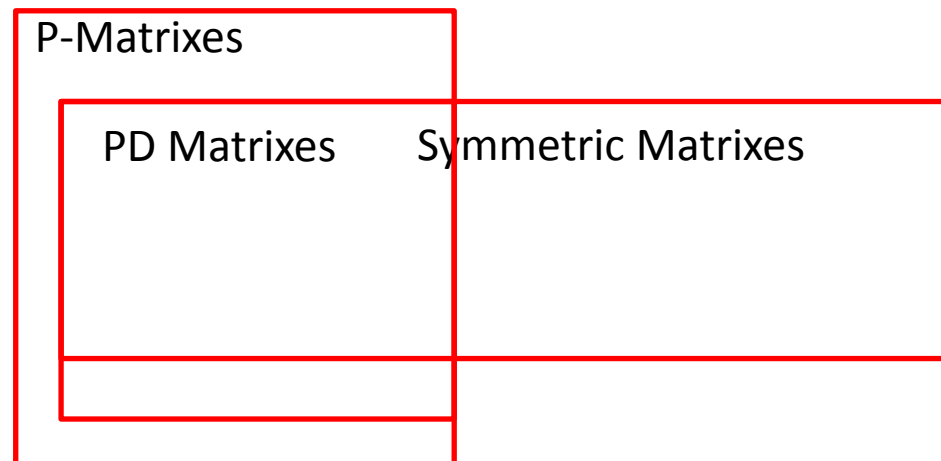
Relation of P-matrixes to positive definite (PD) matrixes:

Reminder(PD):

$$x' M x > 0 \quad \forall x \neq 0$$

Reminder(PSD):

$$x' M x \geq 0 \quad \forall x$$



Computation (Algorithms)

- Naive algorithm, runs on all subsets alpha (intractable)
- Generally, LCP is NP complete
- Lemke's Algorithm, a bit like simplex
- If M is PSD: polynomial time algorithms exists
- PD LCP equivalent to QP
- Special cases of M, linear number of iterations
- Note: Checking for P-Matrix is NP complete, checking for PD is polynomial time
- For our special case we have an algorithm with a quadratic number of iterations

(Still have not done: proven uniqueness using LCP theory).

Show: $(I - Q')^{-1}(I - P')$ is a P matrix

How does LCP generalize LP and QP?

Linear Programming (LP)

Primal-LP:

$$\begin{aligned} \min \quad & c'x \\ \text{s.t.} \quad & Ax \geq b \\ & x \geq 0 \end{aligned}$$

$$\begin{aligned} \min \quad & c'x \\ \text{s.t.} \quad & Ax - b = v \\ & x, v \geq 0 \end{aligned}$$

Dual-LP:

$$\begin{aligned} \max \quad & b'y \\ \text{s.t.} \quad & A'y \leq c \\ & y \geq 0 \end{aligned}$$

$$\begin{aligned} \max \quad & b'y \\ \text{s.t.} \quad & u = c - A'y \\ & y, u \geq 0 \end{aligned}$$

Theorem: Complementary slackness conditions

Assume x, v, y, u are feasible for primal and dual:

$$x_i u_i = 0, \quad y_i v_i = 0 \quad \Leftrightarrow \quad \text{They are optimal solutions}$$

The LCP of LP

Find: $u, v, x, y \geq 0$

Such that:

$$\begin{bmatrix} u \\ v \end{bmatrix} - \begin{bmatrix} 0 & -A' \\ A & 0 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} c \\ -b \end{bmatrix}$$

And (complementary slackness):

$$u'x = 0 \quad v'y = 0$$

$$LCP \left(\begin{bmatrix} c \\ -b \end{bmatrix}, \begin{bmatrix} 0 & -A' \\ A & 0 \end{bmatrix} \right)$$

Quadratic Programming

$$\min Q(x) = c'x + \frac{1}{2}x'Dx$$

$$\text{QP: } s.t. \quad Ax \geq b$$

$$x \geq 0$$

Lemma: An optimizer, \bar{x} , of the QP also optimizes

$$\min (c + D\bar{x})'x$$

$$\text{QP-LP: } s.t. \quad Ax \geq b$$

$$x \geq 0$$

Proof:

Let \hat{x} be feasible. $0 < \eta < 1$, $x_\eta = \bar{x} + \eta(\hat{x} - \bar{x})$

$$Q(x_\eta) - Q(\bar{x}) \geq 0$$

$$(c' + D\bar{x})'(\hat{x} - \bar{x}) \geq \frac{-\eta}{2}(\hat{x} - \bar{x})'D(\hat{x} - \bar{x})$$

$$(c' + D\bar{x})'(\hat{x} - \bar{x}) \geq 0$$

$$(c' + D\bar{x})'\hat{x} \geq (c' + D\bar{x})'\bar{x}$$

QP-LP gives a necessary condition for optimality of QP in terms of an checking optimality of an LP



The Resulting LCP of QP

$$LCP \left(\begin{bmatrix} c \\ -b \end{bmatrix}, \begin{bmatrix} D & -A' \\ A & 0 \end{bmatrix} \right)$$

Allows to find “suspect” points that satisfy the necessary conditions: QP-LP

Theorem: Solutions of this LCP are KKT (Karush-Kuhn-Tucker) points for the QP

Proof: Write down KKT conditions and check.

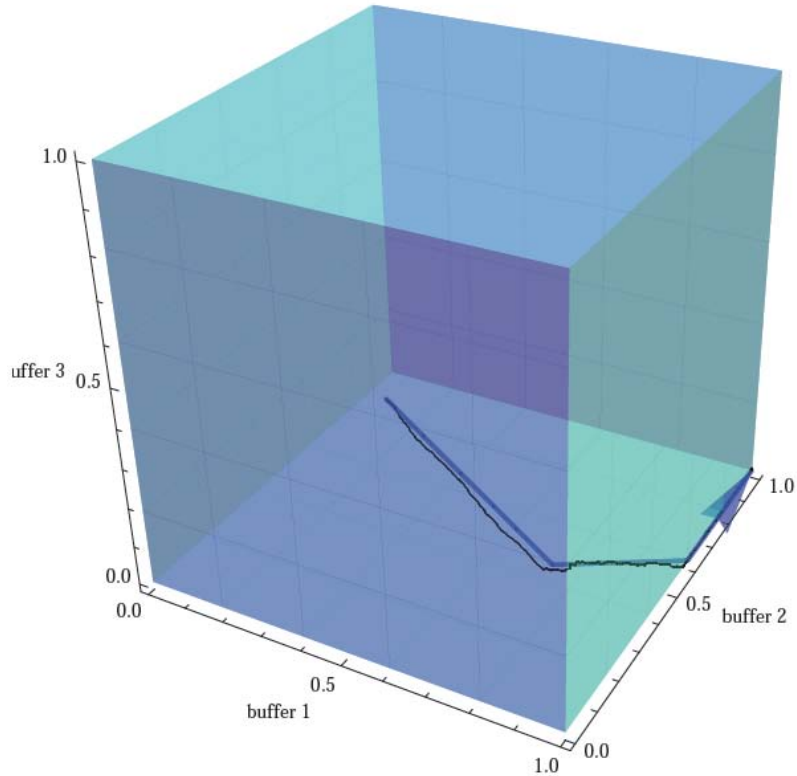
Corollary: If D is PSD then x solving the LCP optimizes QP.

Note: When D is PSD then M is PSD. In this case it can be shown that the LCP is equivalent to a QP (solved in polynomial time). Similarly, every PSD LCP can be formulated as a PSD QP.

Back To Our Problem: The Fluid Network

Limiting Trajectories

In similar spirit to the traffic equations, limiting trajectories, $x(t)$, may be calculated...



We think:

$$\lim_{N \rightarrow \infty} \sup_t \left\{ \left| \frac{X^N(t)}{N} - x(t) \right| \right\} = 0 \quad \text{a.s.}$$

Sojourn Times

Sojourn Time \equiv Time in system of customer arriving
to steady state FCFS system

$S^N \equiv$ Sojourn time of customer in N 'th scaled system

We want to find the limiting distribution of S^N

Construction of Limiting Sojourn Times

$$F = \{1, \dots, s\}$$

$$\lambda_i > \mu_i \text{ for } i \in S$$

$$\bar{F} = \{s+1, \dots, M\}$$

$$\lambda_i < \mu_i \text{ for } i \in \bar{S}$$

Observe,

$$\text{time through } i \in F \approx \frac{K_i}{\mu_i} \quad \text{time through } i \in \bar{F} \approx 0$$

For job at entrance of buffer $i \in F$

$$w.p. \approx \frac{\mu_i}{\lambda_i} \text{ enters buffer } i$$

$$w.p. \approx \left(1 - \frac{\mu_i}{\lambda_i}\right) q_{ij} \text{ routed to entrance of buffer } j$$

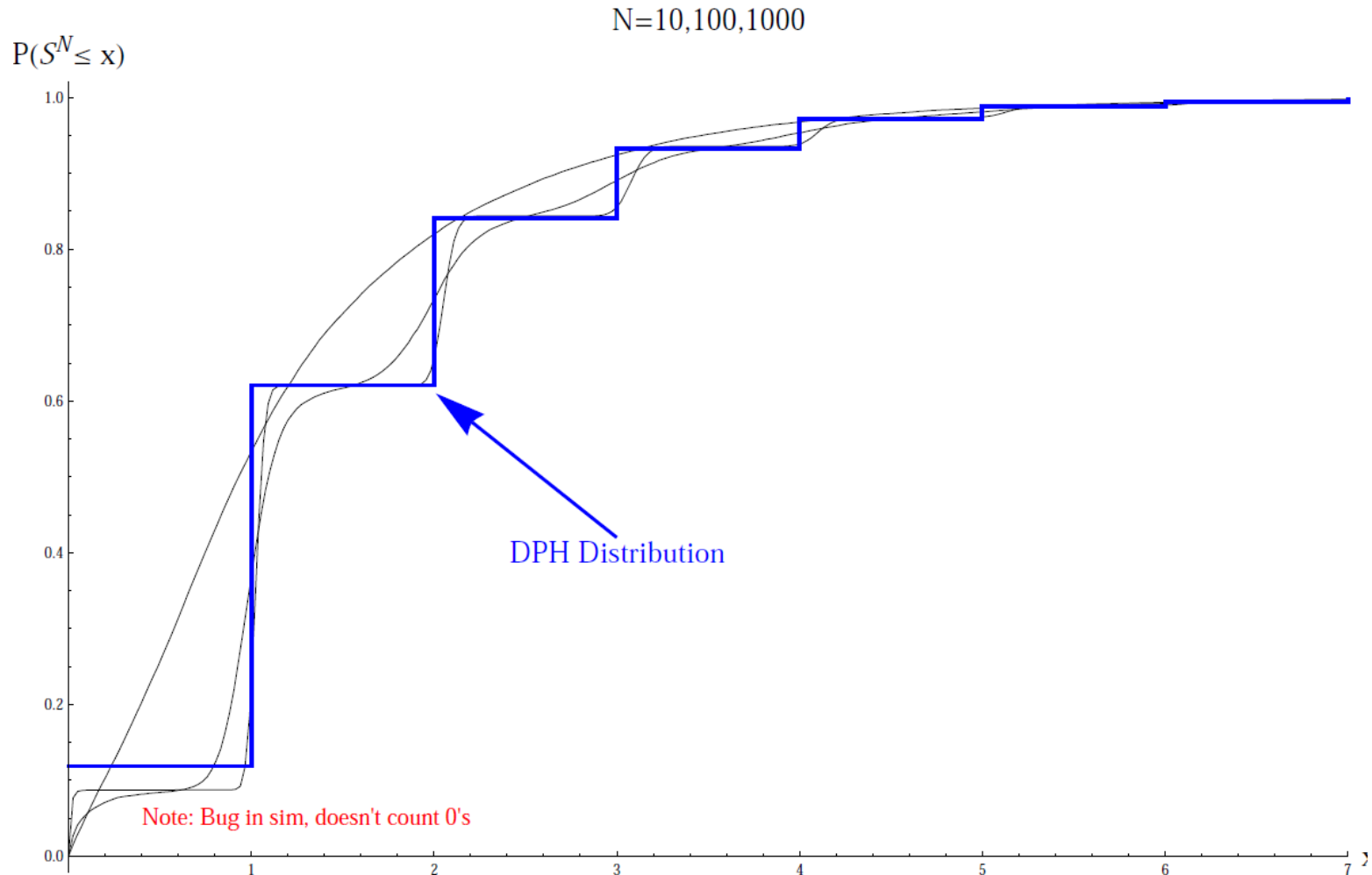
$$w.p. \approx \left(1 - \frac{\mu_i}{\lambda_i}\right) \bar{q}_i \text{ leaves the system}$$

A job at entrance of buffer $i \in \bar{F}$ routed almost immediately according to P

A “fast” chain and “slow” chain...

Sojourn Times Scale to a Discrete Distribution!!!

We think: $\frac{K_i}{\mu_i} = 1, i \in F \quad S^N \Rightarrow DPH(T_{s \times s}, \tau_{1 \times s})$



The “Fast” Chain and “Slow” Chain

Example: $M = 4,$

$$\frac{K_1}{\mu_1} = \frac{K_2}{\mu_2} = 1, \sum_{i=1}^4 \alpha_i = 1,$$

$F = \{1, 2\}, \bar{F} = \{3, 4\} :$

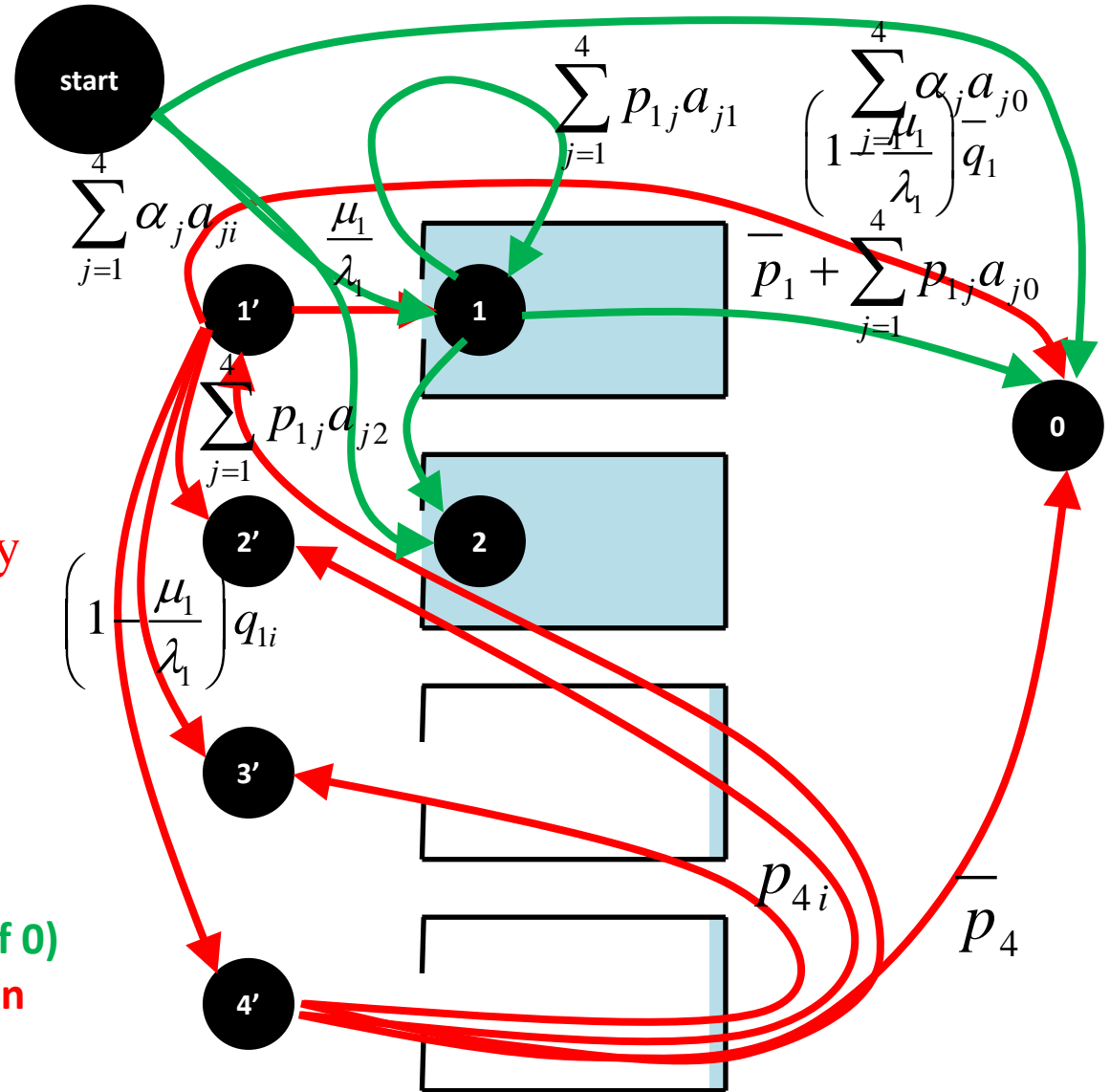
“Fast” chain

on $\{0, 1, 2, 1', 2', 3', 4'\} :$

$a_{ij} \equiv$ Absorption probability
in $j \in \{0, 1, 2\}$ starting in i'

“Slow” chain on $\{0, 1, 2\}$

DPH distribution (hitting time of 0)
transitions based on “Fast” chain



The DPH Parameters (Details)

$$F = \{1, \dots, s\}, \quad \bar{F} = \{s+1, \dots, M\}$$

“Fast” chain

$$B_{M \times s} = \begin{bmatrix} \mu_1 / \lambda_1 & & 0 \\ & \ddots & \\ 0 & & \mu_s / \lambda_s \\ & & & 0_{M-s \times s} \end{bmatrix} \quad C_{M \times M} = \begin{bmatrix} 1 - \frac{\mu_1}{\lambda_1} & & & \\ & \ddots & & \\ & & 1 - \frac{\mu_s}{\lambda_s} & \\ & & & 0_{M-s \times M-s} \end{bmatrix} \cdot Q + \begin{bmatrix} & 0_{s \times M-s} \\ 0_{M \times s} & I_{M-s} \end{bmatrix} \cdot P$$

$$A_{M \times s} = (I - C)^{-1} \cdot B$$

“Slow” chain

$$T_{s \times s} = \begin{bmatrix} I_s & 0_{s \times M-s} \end{bmatrix} \cdot P \cdot A \quad \tau_{s \times 1} = \frac{1}{\sum_{j=1}^M \alpha_j} \alpha^T \cdot A$$

$$S \sim DPH(T_{s \times s}, \tau_{1 \times s}) \quad P(S \leq k) = 1 - \tau \cdot T^k \cdot \mathbf{1}_{s \times 1}$$

Mechanism of nonlinear flow pattern selection in moderately non-Boussinesq mixed convection

Yoni Nazarathy, Sergey Suslov,
John Beynon, William Phillips

Swinburne Applied Mathematics Seminar,
April **1**, 2011.